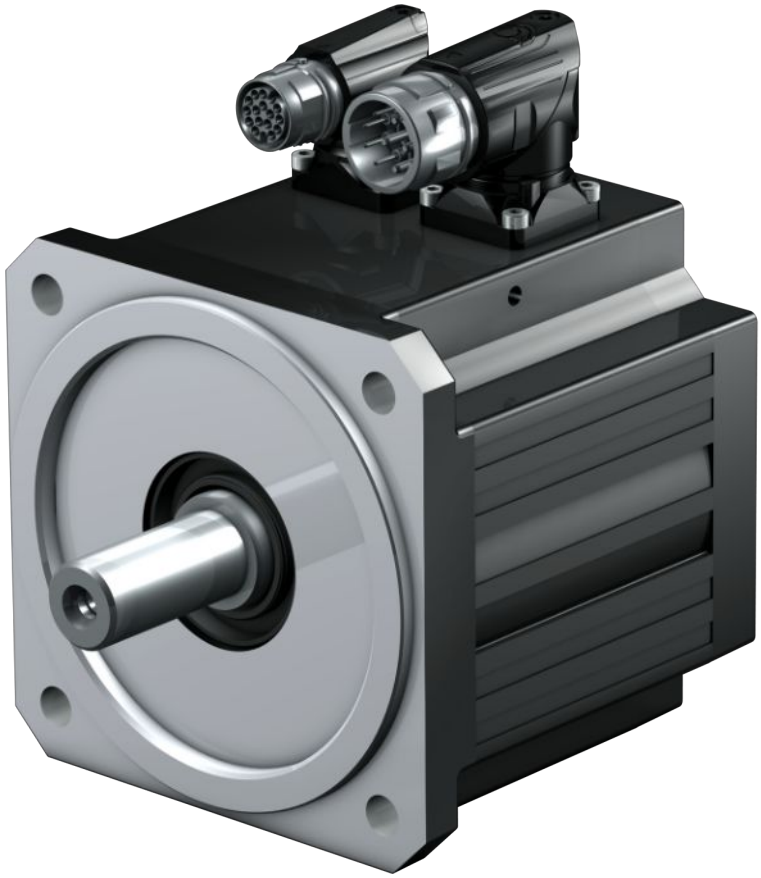

EZ motors in combination with Beckhoff AX5000/AX8000
Information on compatibility

en-US
04/2026
ID 443185_en.04

STÖBER

Table of contents

04/2026 | ID 443185_en.04

1 Foreword

The STOBER synchronous servo motors of the EZ series can be operated with drive controllers from a wide range of manufacturers – for example with the AX5000/AX8000 servo drives from Beckhoff (referred to below as drive controllers).

The encoders, temperature sensors, plug connectors and terminal assignments of the STOBER motors are compatible with the aforementioned drive controllers. We recommend using only original cables from Beckhoff.

04/2026 | ID 443185_en.04

2 Information on this documentation

This documentation contains information on the compatibility of STOBER synchronous servo motors of the EZ series with the AX5000/AX8000 drive controllers from Beckhoff. The relevant operating manual applies to installation, connection and commissioning.

2.1 Timeliness

Check whether you have the latest version of this documentation. The latest document versions for our products are available for download on our website:
http://www.stoeber.de/en/downloads/.

2.2 Original language

The original language of this documentation is German; all other language versions are derived from the original language.

2.3 Limitation of liability

This documentation was created taking into account the applicable standards and regulations as well as the current state of technology.

No warranty or liability claims for damage shall result from failure to comply with the documentation or from use that deviates from the intended use of the product. This is especially true for damage caused by individual technical modifications to the product or the project configuration and operation of the product by unqualified personnel.

2.4 Formatting conventions

Orientation guides in the form of signal words, symbols and special text markups are used to emphasize specific information so that you are able identify it in this documentation quickly.

2.4.1 Distinction of text elements

Certain elements of the continuous text are distinguished as follows.

Important information	Words or expressions with a special meaning
Interpolated position mode	Optional: File or product name or other name
Detailed information	Internal cross-reference
http://www.samplelink.com	External cross-reference

04/2026 | ID 443185_en.04

2.5 Trademarks

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TwinCAT®	TwinCAT® is a registered and licensed trademark of Beckhoff Automation GmbH, Germany.

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Products that are registered as trademarks are not specially indicated in this documentation. Existing property rights (patents, trademarks, protection of utility models) are to be observed.

04/2026 | ID 443185_en.04

3 Connection

The terminal assignment of the plug connectors of STOBER synchronous servo motors of the EZ series – in the version for Beckhoff drive controllers – is identical to that of the motors from Beckhoff. The customer can therefore obtain and connect the corresponding Beckhoff original cables. STOBER does not offer any connection cables for Beckhoff drive controllers, but can recommend an appropriate cable family on request.

3.1 Possible combinations with drive controllers

The following table shows the possible combinations of STOBER synchronous servo motors with drive controllers from Beckhoff depending on the encoder model.

Drive controller		**AX5000 8-pin**[1] EnDat 2.1	**AX8000/5000 OCS 9-pin**[2] HIPERFACE DSL	**AX5000 9-pin**[3] EnDat 2.1	**AX8000 9-pin**[4] EnDat 2.2
Drive controller code		FM	HK	HN	HO
Connection plan ID		442318	443393	443451	443452
Encoder	**Encoder code**				
EnDat 2.2 EQI 1131 Safety	S2				EZ
EnDat 2.2 EQN 1135 Safety	S3				EZ
EnDat 2.1 EQN 1125	Q4	EZ		EZ	
EnDat 2.1 EQI 1130-G3	Q2			EZ	
EDM35	H6		EZ		

The encoder and drive controller codes are a part of the type designation of the motor.

3.2 Encoders

Encoders with EnDat 2.2 interface

Encoder model	Code	Measuring method	Recordable revolutions	Resolution	Position values per revolution	MTTF [years]	PFH [h]
EnDat 2.2 EQI 1131 Safety	S2	Inductive	4096	19 bit	524288	> 100	$\leq 15 \times 10^{-9}$
EnDat 2.2 EQN 1135 Safety	S3	Optical	4096	23 bit	8388608	> 100	$\leq 15 \times 10^{-9}$

[1] Design of the power connector
[2] Design of the power connector
[3] Design of the power connector
[4] Design of the power connector

04/2026 | ID 443185_en.04

Encoders with EnDat 2.1 interface

Encoder model	Code	Measuring method	Recordable revolutions	Resolution	Position values per revolution	Periods per revolution	MTTF [years]	PFH [h]
EnDat 2.1 EQN 1125	Q4	Optical	4096	13 bit	8192	Sin/cos 512	> 57	$\leq 2 \times 10^{-6}$
EnDat 2.1 EQI 1130-G3	Q2	Inductive	4096	18 bit	262144	Sin/cos 16	> 100	$\leq 6 \times 10^{-7}$

Encoders with HIPERFACE DSL interface

Encoder model	Code	Measuring method	Recordable revolutions	Resolution	Position values per revolution	MTTF [years]	PFH [h]
EDM35	H6	Optical	4096	20 bit	1048576	> 100	$\leq 31 \times 10^{-9}$

Notes

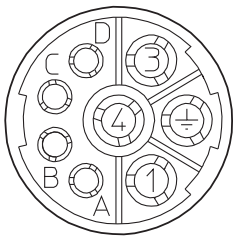
- The encoder code is a part of the type designation of the motor.
- Safety = Safety-related position measuring system for use in safety-oriented applications.
- Multiple revolutions of the motor shaft can be recorded only using multi-turn encoders.

3.3 Two-cable solution

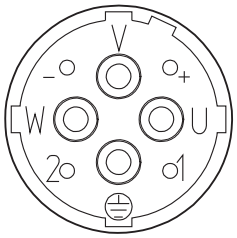
3.3.1 Terminal assignment of 8-pin power plug connector

The size and connection diagram of the power plug connector depend on the size of the motor.

Plug connector size con.23

Connection diagram	Pin	Connection
	1	1U1 (U phase)
	3	1W1 (W phase)
	4	1V1 (V phase)
	A	1BD1 (brake +)
	B	1BD2 (brake −)
	C	1TP1 (temperature sensor +)
	D	1TP2 (temperature sensor −)
	⏚	PE (grounding conductor)

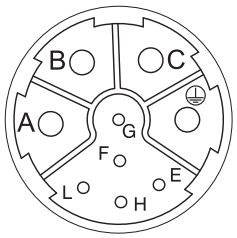
Plug connector size con.40

Connection diagram	Pin	Connection
	U	1U1 (U phase)
	V	1V1 (V phase)
	W	1W1 (W phase)
	+	1BD1 (brake +)
	–	1BD2 (brake –)
	1	1TP1 (temperature sensor +)
	2	1TP2 (temperature sensor –)
	⏚	PE (grounding conductor)

3.3.2 Terminal assignment of 9-pin power plug connector

The size and connection diagram of the power plug connector depend on the size of the motor.

Plug connector size con.23

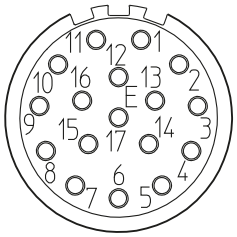
Connection diagram	Pin	Connection
	A	1U1 (U phase)
	B	1V1 (V phase)
	C	1W1 (W phase)
	E	1TP2 (temperature sensor -)
	F	
	G	1BD1 (brake +)
	H	1TP1 (temperature sensor +)
	L	1BD2 (brake –)
	⏚	PE (grounding conductor)

04/2026 | ID 443185_en.04

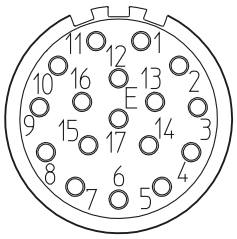
3.3.3 Connection assignment of the encoder plug connector

The size and terminal assignment of the encoder plug connectors depend on the type of encoder installed and the size of the motor.

EnDat 2.2 digital encoder, plug connector size con.23

Connection diagram	Pin	Connection
	1	
	2	0 V GND
	3	
	4	Up +
	5	Data +
	6	
	7	
	8	Clock +
	9	
	10	0 V sense
	11	
	12	Up sense
	13	Data –
	14	
	15	Clock –
	16	
	17	

EnDat 2.1 encoder with sin/cos incremental signals, plug connector size con.23

Connection diagram	Pin	Connection
	1	B – (Sin –)
	2	0 V GND
	3	A – (Cos –)
	4	Up +
	5	Data +
	6	
	7	
	8	Clock +
	9	B + (Sin +)
	10	0 V sense
	11	A + (Cos +)
	12	Up sense
	13	Data –
	14	
	15	Clock –
	16	
	17	

04/2026 | ID 443185_en.04

3.3.4 Plug connectors

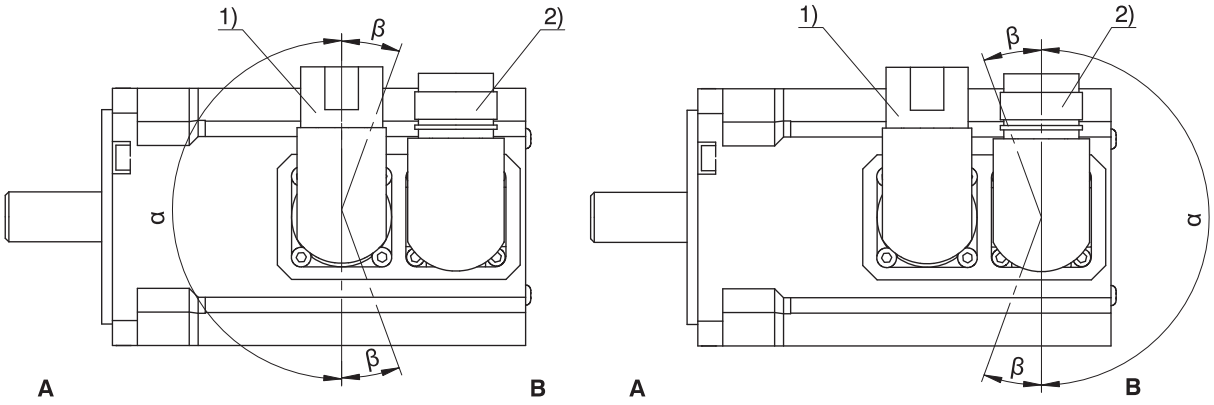
In the standard version, STOBER synchronous servo motors are equipped with rotatable plug connectors[5] for power and encoder connections. You can find detailed technical information about the plug connectors at http://www.intercontec.biz.

For motors with forced ventilation, avoid collisions between the motor connection cables and the plug connector of the forced ventilation unit. In the event of a collision, rotate the plug connectors of the motor by the required angle.

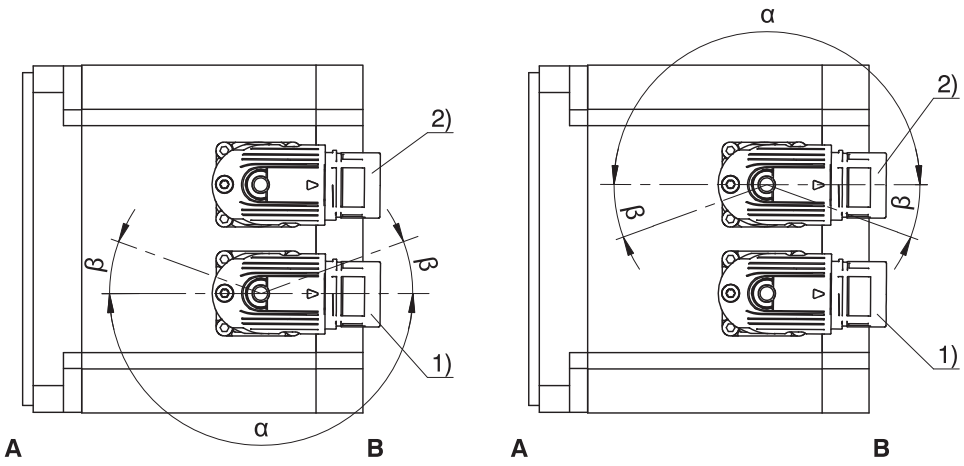
For winding protection, STOBER uses PTC or Pt1000 temperature sensors, which are selected to match the drive. In a two-cable solution, the temperature sensor connections are routed via the power plug connector.

The figures represent the position of the plug connectors upon delivery.

Turning ranges of plug connectors (EZ2 – EZ3 motors)



Turning ranges of plug connectors (EZ4 – EZ8 motors)



1	Power plug connector	2	Encoder plug connector
A	Attachment or output side of the motor	B	Not output side

[5] The connectors can be pivoted up to 10 times at a specific angle. They cannot be rotated repeatedly.

Power plug connector features

Motor type	Size	Connection	Turning range	
			α	β
EZ2, EZ3	con.23	Quick-lock	180°	120°
EZ4, EZ5, EZ701, EZ702, EZ703	con.23	Quick-lock	180°	40°
EZ705, EZ8	con.40	Quick-lock	180°	40°

Encoder plug connector features

Motor type	Size	Connection	Turning range	
			α	β
EZ2, EZ3	con.23	Quick-lock	180°	120°
EZ4, EZ5, EZ7, EZ8	con.23	Quick-lock	190°	35°

Notes

- The number after "con." indicates the approximate external thread diameter of the plug connector in mm (for example, con.23 designates a plug connector with an external thread diameter of about 23 mm).
- In turning range β, the power or encoder plug connectors can be turned only if doing so does not cause them to collide.

04/2026 | ID 443185_en.04

3.4 One Cable Solution

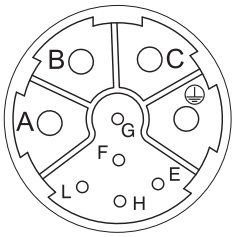
3.4.1 Terminal assignment for plug connectors (One Cable Solution)

In the One Cable Solution design, the power and encoder lines are connected using a shared plug connector.

The size of the plug connector depends on the size of the motor.

The temperature sensor of the motor is connected to the encoder internally. The measured values from the temperature sensor are transmitted via the log of the encoder.

Plug connector size con.23

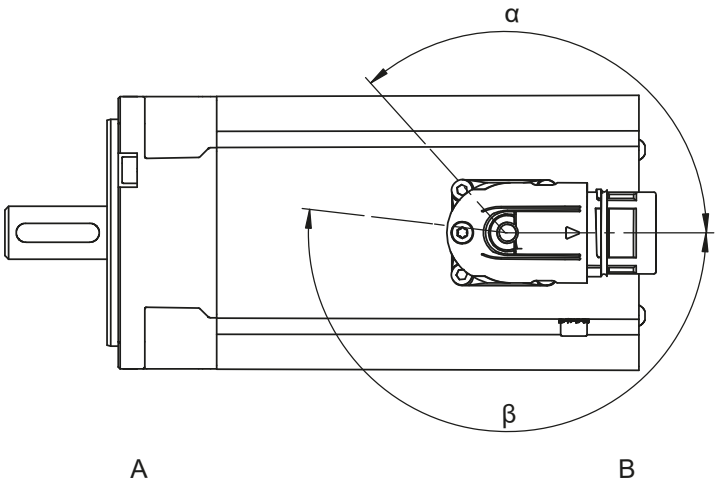
Connection diagram	Pin	Connection
	A	1U1 (U phase)
	B	1V1 (V phase)
	C	1W1 (W phase)
	E	DSL– (L)
	F	DSL shield
	G	1BD1
	H	DSL+ (H)
	L	1BD2
	⏚	PE (grounding conductor)

3.4.2 Plug connectors (One Cable Solution)

For motors with forced ventilation, avoid collisions between the motor connection cables and the plug connector of the forced ventilation unit. In the event of a collision, rotate the plug connectors of the motor by the required angle.

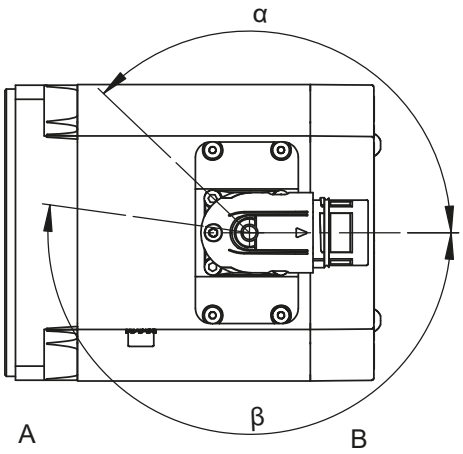
The figures represent the position of the plug connectors upon delivery.

Turning ranges of plug connectors (EZ2 – EZ3 motors)



A	Attachment or output side of the motor	B	Not output side

Turning ranges of plug connectors (EZ4 – EZ7 motors)



A	Attachment or output side of the motor	B	Not output side

Plug connector features

Motor type	Size	Connection	Turning range	
			α	β
EZ2 – EZ5, EZ701 – EZ703, EZ705U, EZ705B (n_N=3000 rpm)	con.23	Quick-lock	130°	190°

Notes

- The number after "con." indicates the approximate external thread diameter of the plug connector in mm (for example, con.23 designates a plug connector with an external thread diameter of about 23 mm).

04/2026 | ID 443185_en.04

4 Commissioning

Only put the motor into operation if you have reviewed its installation and connection in accordance with the associated operating manual, as well as all other necessary requirements specific to your system. In addition, follow the instructions for commissioning your drive controller in the third-party manufacturer's documentation.

4.1 Parameterizing the motor

After the motor has been installed and connected to the corresponding drive controller, parameterization takes place in Beckhoff's TwinCAT commissioning software.

As a specific parameterization list is required for this, please contact STOBER System Support at systemsupport@stoeber.de and send either your order number or the series, size and type designation of the motor as well as the type of drive controller used. You will receive the requested list immediately by e-mail.

The electronic nameplate of STOBER motors is stored in the encoder memory. With Beckhoff drive controllers up to firmware version 2.06, the motor can be detected and the necessary motor parameters read out using Beckhoff's TwinCAT software.

Information

The commutation offset of the motor comes from the factor set in such a way that calibration by the customer is not necessary.

04/2026 | ID 443185_en.04

5 Appendix

5.1 Further information

The documentation listed below provides you with further relevant information on the motors. The current status of the documentation can be found in our download center at:
http://www.stoeber.de/en/downloads/.
Enter the ID of the documentation in the search.

Title	Documentation	Contents	ID
Synchronous Servo Motors EZ	Operating manual	Technical data, transport and storage, installation, connection, commissioning, service	443032_en

The documentation for the drive controllers and a current version of the TwinCAT commissioning software are available in the download area of Beckhoff at:
https://www.beckhoff.com/en-us/support/download-finder/.

5.2 Abbreviations

Abbreviation	Meaning
GND	Ground
OCS	One Cable Solution
PE	Protective Earth (grounding conductor)
PTC	Positive Temperature Coefficient

04/2026 | ID 443185_en.04

6 Contact

6.1 Consultation, service and address

We would be happy to help you!

We offer a wealth of information and services to go with our products on our website:
http://www.stoeber.de/en/service

For additional or personalized information, contact our consultation and support service:
http://www.stoeber.de/en/support

If you need our system support:
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Call our 24-hour service hotline:
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Our address is:
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75177 Pforzheim, Germany

6.2 Your opinion is important to us

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If you want to contact us for a specific reason, we would be happy to receive an e-mail from you at:
documentation@stoeber.de

Thank you for your interest.
Your STOBER editorial team

04/2026 | ID 443185_en.04

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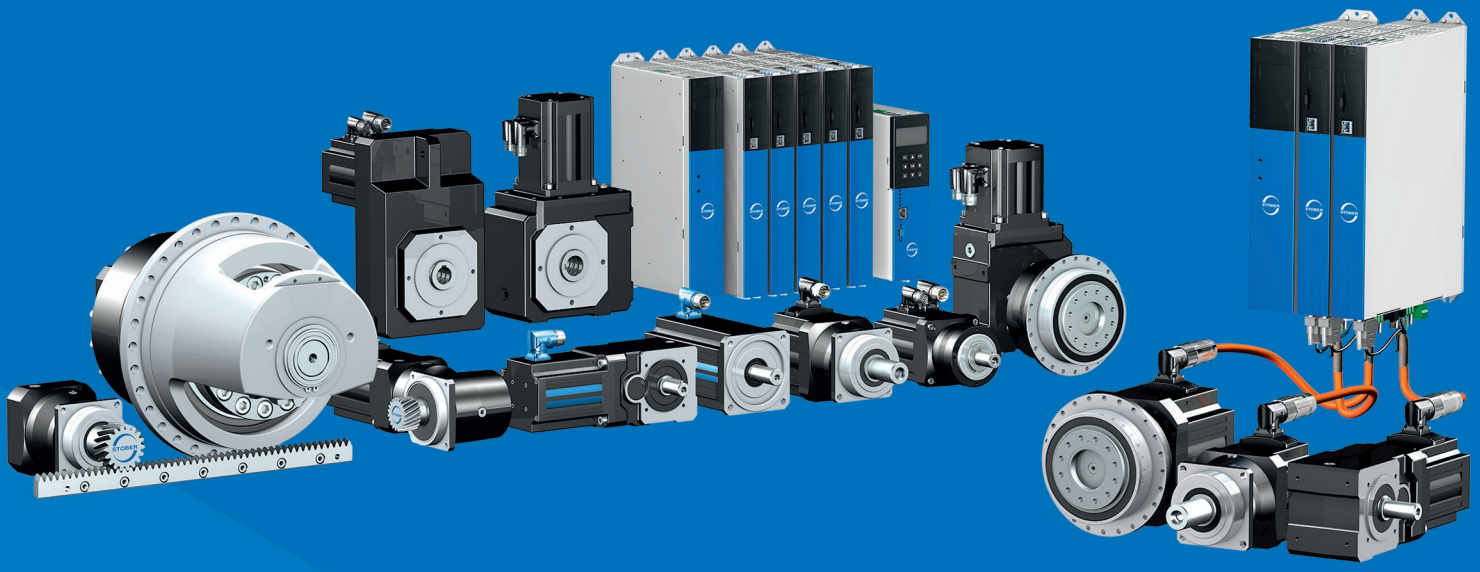
04/2026 | ID 443185_en.04



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