7.3 Dimensional drawings

In this chapter you can find the dimensions of the geared motors.

There is a dimensional drawing for every possible shaft/housing design, each with the tables for gear unit dimensions, motor dimensions and geared motor dimensions.

Dimensions can exceed the specifications of ISO 2768-mK due to casting tolerances or accumulation of individual tolerances.

We reserve the right to make dimensional changes due to ongoing technical development.

You can download 3D models of our standard drives at https://configurator.stoeber.de/en-US/.

Combination options and the dimensions of forced ventilated geared motors can also be found at https://configurator.stoeber.de/en-US/.

Tolerances

Axis height in accordance with DIN 747	Tolerance
Up to 50 mm	-0.4 mm
Up to 250 mm	-0.5 mm
Up to 630 mm	-0.6 mm

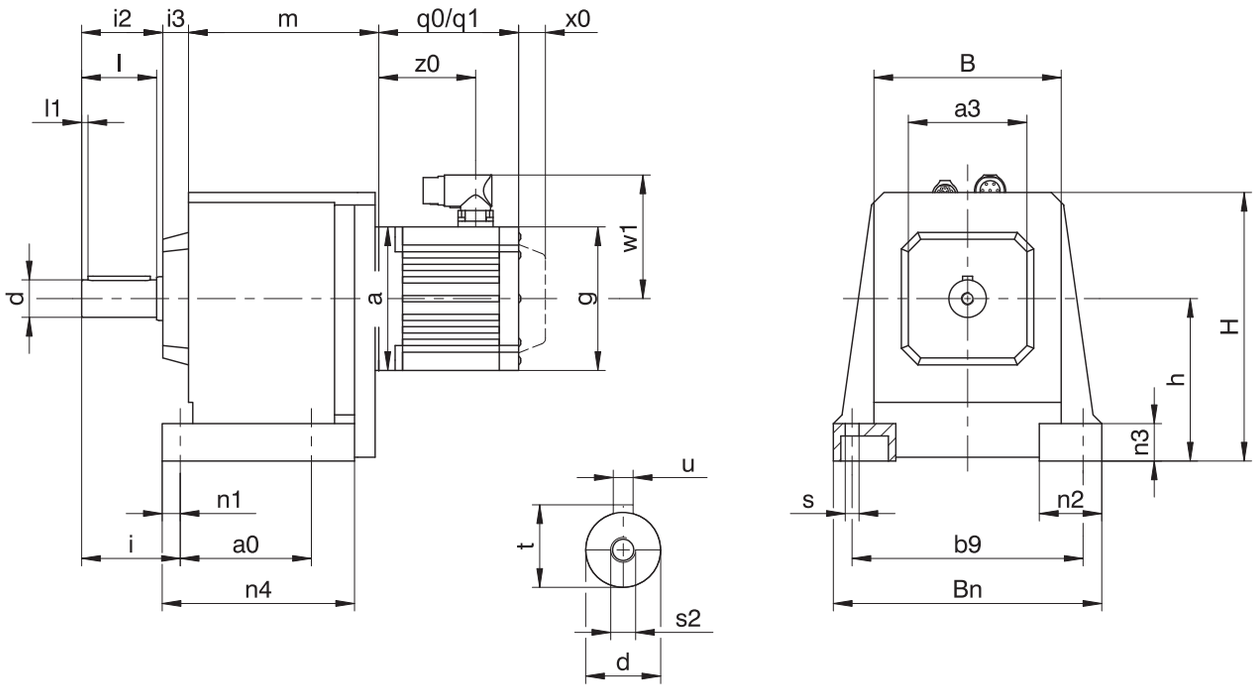
Solid shaft	Tolerance
Shaft ∅ fit ≤ 50 mm	DIN 748-1, ISO k6
Shaft ∅ fit > 50 mm	DIN 748-1, ISO m6
Feather keys	DIN 6885-1, high form A

Flange	Pilot tolerance
Up to 300 mm	ISO j6
Starting at 350 mm	ISO h6

Centering holes in solid shafts in accordance with DIN 332-2, DR shape

Thread size	M4	M5	M6	M8	M10	M12	M16	M20	M24
Thread depth [mm]	10	12.5	16	19	22	28	36	42	50

7.3.1 Solid shaft design with feather key, N housing design (foot)



q0	Applies to motors without brake.	q1	Applies to motors with brake.
x0	EZ2: Applies only to motors with brake and encoders using an optical or inductive measuring method EZ3 – EZ8: Applies to encoders using an optical measuring method	w1	Different for the One Cable Solution (OCS), see the chapter [▷ 17.4]

C203, C303, C612, C613: Motor and gear unit are sometimes non-coaxial.

Options: C0 – C5 also available with solid shaft without feather key; on request starting at C6.

Dimensions of gear units

Type	a0	a3	b9	B	Bn	Ød	h	H	i	i2	i3	l	l1	n1	n2	n3	n4	Øs	s2	t	u
C0	62	60	110	92	132	20_{k6}	82	144	55	44	13	40	3	11	35	20	95.0	7	M6	22.5	A6×6×32
C1	70	80	150	124	176	25_{k6}	102	177	67	54	15	50	5	13	42	25	117.5	9	M10	28.0	A8×7×40
C2	85	95	170	138	200	30_{k6}	115	195	79	65	21	60	5	14	50	30	134.5	11	M10	33.0	A8×7×50
C3	105	95	185	150	215	30_{k6}	130	215	79	65	20	60	5	14	50	30	153.5	11	M10	33.0	A8×7×50
C4	110	110	220	175	255	40_{k6}	145	245	105	86	20	80	5	19	60	35	180.0	14	M16	43.0	A12×8×70
C5	130	130	245	192	290	40_{k6}	170	290	108	86	21	80	5	22	70	40	197.0	18	M16	43.0	A12×8×70
C6	215	177	245	225	300	50_{k6}	200	315	130	106	47	100	5	25	75	40	265.0	18	M16	53.5	A14×9×90
C7	235	192	300	265	365	60_{m6}	235	375	163	127	58	120	5	25	90	50	285.0	18	M20	64.0	A18×11×100
C8	300	223	340	310	435	70_{m6}	290	450	190	148	70	140	5	29	95	55	360.0	22	M20	74.5	A20×12×125
C9	340	277	400	365	510	90_{m6}	340	530	222	178	78	170	5	34	110	60	410.0	26	M24	95.0	A25×14×140

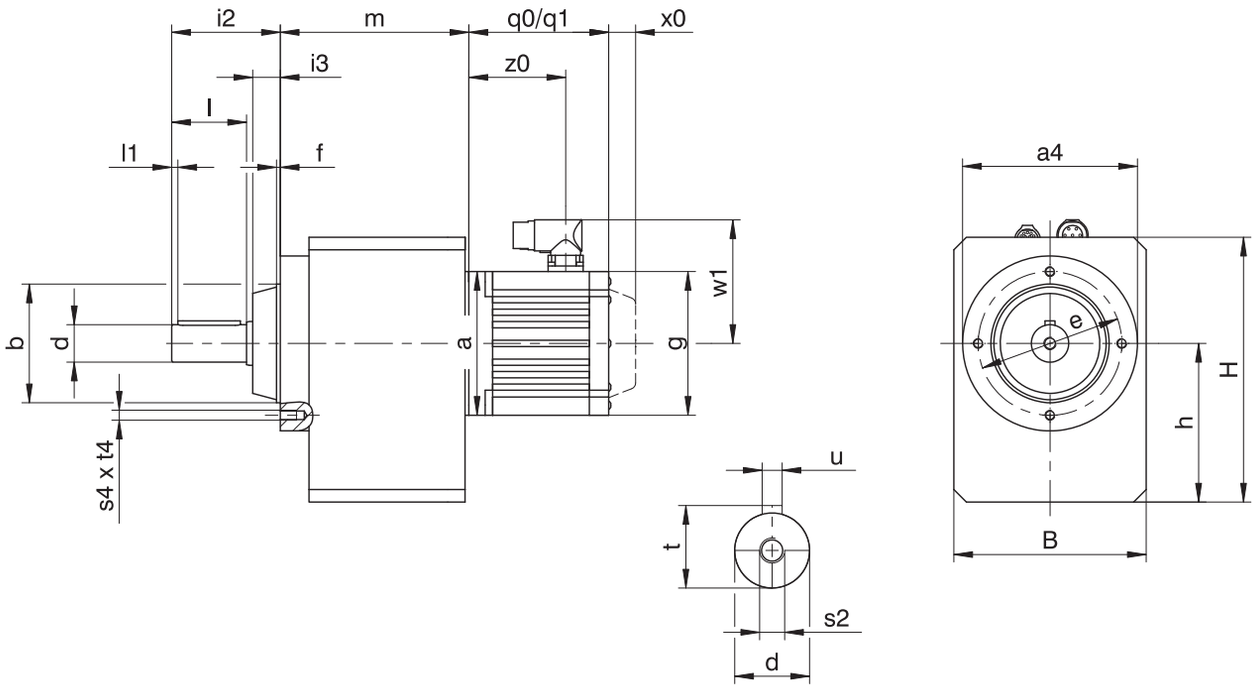
Dimensions of motors

Type	□g	q0	q1	w1	x0	z0
EZ203U	55	166.0	175.0	47.0	25	111.0
EZ301U	72	114.0	154.0	55.5	21	78.5
EZ302U	72	136.0	176.0	55.5	21	100.5
EZ303U	72	158.0	198.0	55.5	21	122.5
EZ401U	98	118.5	167.0	91.0	22	76.5
EZ402U	98	143.5	192.0	91.0	22	101.5
EZ404U	98	193.5	242.0	91.0	22	151.5
EZ501U	115	112.0	166.5	100.0	22	77.5
EZ502U	115	137.0	191.5	100.0	22	102.5
EZ503U	115	162.0	216.5	100.0	22	127.5
EZ505U	115	212.0	266.5	100.0	22	177.5
EZ701U	145	125.0	184.0	115.0	22	87.0
EZ702U	145	150.0	209.0	115.0	22	112.0
EZ703U	145	175.0	234.0	115.0	22	137.0
EZ705U	145	230.0	289.0	134.0	22	188.0
EZ802U	190	232.5	309.5	156.5	22	178.5
EZ803U	190	273.5	350.5	156.5	22	219.5
EZ805U	190	355.5	432.5	156.5	22	301.5

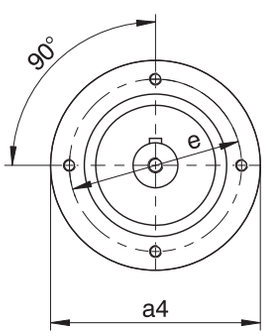
Dimensions of geared motors

Type	EZ2		EZ3		EZ4		EZ5		EZ7		EZ8	
	a	m	a	m	a	m	a	m	a	m	a	m
C002	□55	97.5	□72	97.5	□98	97.5	□115	101.5	□145	103.5	–	–
C102	–	–	□72	118.0	□98	118.0	□115	122.0	□145	124.0	–	–
C103	–	–	∅140	155.0	–	–	–	–	–	–	–	–
C202	–	–	∅140	129.0	∅140	129.0	□115	133.0	□145	135.0	–	–
C203	–	–	∅140	166.0	∅140	166.0	–	–	–	–	–	–
C302	–	–	–	–	–	–	∅160	152.5	□145	154.5	□190	157.5
C303	–	–	∅140	185.5	∅140	185.5	∅160	195.5	–	–	–	–
C402	–	–	–	–	–	–	∅160	180.0	□145	182.0	□190	185.0
C403	–	–	–	–	–	–	∅160	223.0	–	–	–	–
C502	–	–	–	–	–	–	∅160	200.0	∅200	202.0	□190	205.0
C503	–	–	–	–	–	–	∅160	243.0	–	–	–	–
C612	–	–	–	–	–	–	–	–	∅200	180.0	□190	183.0
C613	–	–	–	–	–	–	∅160	222.0	∅200	242.0	–	–
C712	–	–	–	–	–	–	–	–	∅200	201.0	∅250	203.0
C713	–	–	–	–	–	–	–	–	∅200	262.0	∅250	274.0
C812	–	–	–	–	–	–	–	–	–	–	∅250	237.0
C813	–	–	–	–	–	–	–	–	∅200	296.0	∅250	308.0
C913	–	–	–	–	–	–	–	–	–	–	∅250	337.0

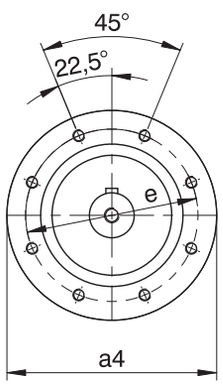
7.3.2 Solid shaft design with feather key, G housing design (pitch circle diameter)



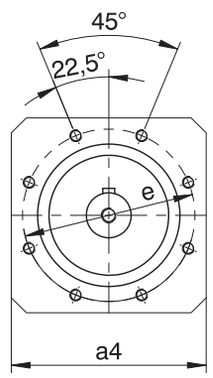
C1 – C4



C5



C6 – C9



q0	Applies to motors without brake.	q1	Applies to motors with brake.
x0	EZ2: Applies only to motors with brake and encoders using an optical or inductive measuring method EZ3 – EZ8: Applies to encoders using an optical measuring method	w1	Different for the One Cable Solution (OCS), see the chapter [▶ 17.4]

C203, C303, C612, C613: Motor and gear unit are sometimes non-coaxial.

Options: C0 – C5 also available with solid shaft without feather key; on request starting at C6.

Dimensions of gear units

Type	a4	Øb	B	Ød	Øe	f	h	H	i2	i3	l	l1	s2	s4	t	t4	u
C0	∅87	55_{j6}	97	20_{k6}	75	3.0	79.0	141.0	58	14	40	3	M6	M6	22.5	10	A6×6×32
C1	∅120	80_{j6}	130	25_{k6}	100	3.0	100.0	175.0	71	17	50	5	M10	M6	28.0	13	A8×7×40
C2	∅140	95_{j6}	142	30_{k6}	115	3.0	112.0	192.0	87	22	60	5	M10	M8	33.0	13	A8×7×50
C3	∅140	95_{j6}	154	30_{k6}	115	3.0	127.0	212.0	87	22	60	5	M10	M8	33.0	13	A8×7×50
C4	∅160	110_{j6}	178	40_{k6}	130	3.5	142.5	242.5	108	22	80	5	M16	M10	43.0	16	A12×8×70
C5	∅192	130_{j6}	195	40_{k6}	165	3.5	166.0	286.0	109	23	80	5	M16	M10	43.0	16	A12×8×70
C6	□180	140_{j6}	225	50_{k6}	165	5.0	195.0	310.0	136	30	100	5	M16	M10	53.5	16	A14×9×90
C7	□195	155_{j6}	265	60_{m6}	185	8.0	231.0	371.0	164	37	120	5	M20	M12	64.0	19	A18×11×100
C8	□226	185_{j6}	310	70_{m6}	215	5.0	285.0	445.0	185	37	140	5	M20	M12	74.5	19	A20×12×125
C9	□280	230_{j6}	365	90_{m6}	265	5.0	334.0	524.0	220	42	170	5	M24	M16	95.0	26	A25×14×140

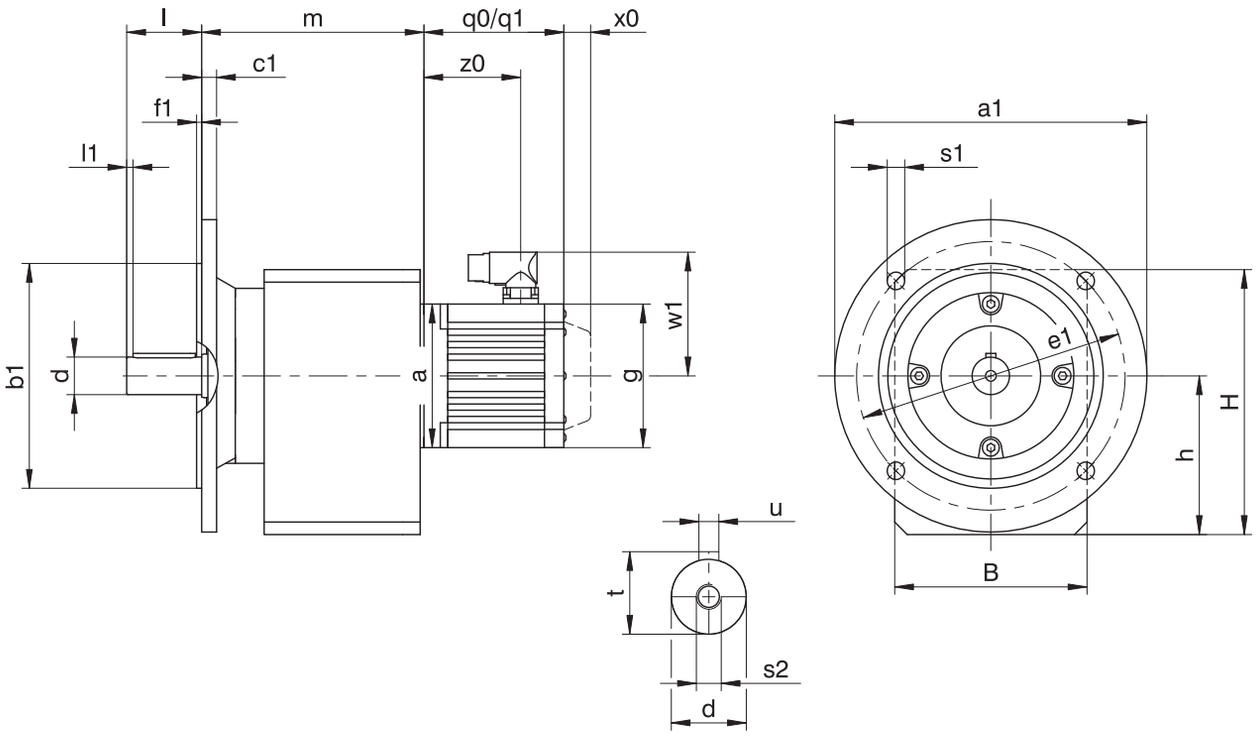
Dimensions of motors

Type	□g	q0	q1	w1	x0	z0
EZ203U	55	166.0	175.0	47.0	25	111.0
EZ301U	72	114.0	154.0	55.5	21	78.5
EZ302U	72	136.0	176.0	55.5	21	100.5
EZ303U	72	158.0	198.0	55.5	21	122.5
EZ401U	98	118.5	167.0	91.0	22	76.5
EZ402U	98	143.5	192.0	91.0	22	101.5
EZ404U	98	193.5	242.0	91.0	22	151.5
EZ501U	115	112.0	166.5	100.0	22	77.5
EZ502U	115	137.0	191.5	100.0	22	102.5
EZ503U	115	162.0	216.5	100.0	22	127.5
EZ505U	115	212.0	266.5	100.0	22	177.5
EZ701U	145	125.0	184.0	115.0	22	87.0
EZ702U	145	150.0	209.0	115.0	22	112.0
EZ703U	145	175.0	234.0	115.0	22	137.0
EZ705U	145	230.0	289.0	134.0	22	188.0
EZ802U	190	232.5	309.5	156.5	22	178.5
EZ803U	190	273.5	350.5	156.5	22	219.5
EZ805U	190	355.5	432.5	156.5	22	301.5

Dimensions of geared motors

Type	EZ2		EZ3		EZ4		EZ5		EZ7		EZ8	
	a	m	a	m	a	m	a	m	a	m	a	m
C002	□55	96	□72	96	□98	96	□115	100	□145	102	–	–
C102	–	–	□72	116	□98	116	□115	120	□145	122	–	–
C103	–	–	∅140	153	–	–	–	–	–	–	–	–
C202	–	–	∅140	128	∅140	128	□115	132	□145	134	–	–
C203	–	–	∅140	165	∅140	165	–	–	–	–	–	–
C302	–	–	–	–	–	–	∅160	151	□145	153	□190	156
C303	–	–	∅140	184	∅140	184	∅160	194	–	–	–	–
C402	–	–	–	–	–	–	∅160	178	□145	180	□190	183
C403	–	–	–	–	–	–	∅160	221	–	–	–	–
C502	–	–	–	–	–	–	∅160	198	∅200	200	□190	203
C503	–	–	–	–	–	–	∅160	241	–	–	–	–
C612	–	–	–	–	–	–	–	–	∅200	197	□190	200
C613	–	–	–	–	–	–	∅160	239	∅200	259	–	–
C712	–	–	–	–	–	–	–	–	∅200	222	∅250	224
C713	–	–	–	–	–	–	–	–	∅200	283	∅250	295
C812	–	–	–	–	–	–	–	–	–	–	∅250	270
C813	–	–	–	–	–	–	–	–	∅200	329	∅250	341
C913	–	–	–	–	–	–	–	–	–	–	∅250	373

7.3.3 Solid shaft design with feather key, F housing design (round flange)



q0 Applies to motors without brake.

q1 Applies to motors with brake.

x0 EZ2: Applies only to motors with brake and encoders using an optical or inductive measuring method
EZ3 – EZ8: Applies to encoders using an optical measuring method

w1 Different for the One Cable Solution (OCS), see the chapter [▶ 17.4]

C203, C303, C612, C613: Motor and gear unit are sometimes non-coaxial.

Options: C0 – C5 also available with solid shaft without feather key; on request starting at C6.

Dimensions of gear units

Type	Øa1	Øb1	B	c1	Ød	Øe1	f1	h	H	l	l1	Øs1	s2	t	u
C0	160	110_{j6}	97	10	20_{k6}	130	3.0	79.0	141.0	40	3	9	M6	22.5	A6×6×32
C1	200	130_{j6}	130	12	25_{k6}	165	3.5	100.0	175.0	50	5	11	M10	28.0	A8×7×40
C2	200	130_{j6}	142	12	30_{k6}	165	3.5	112.0	192.0	60	5	11	M10	33.0	A8×7×50
C3	250	180_{j6}	154	12	30_{k6}	215	4.0	127.0	212.0	60	5	14	M10	33.0	A8×7×50
C4	250	180_{j6}	178	14	40_{k6}	215	4.0	142.5	242.5	80	5	14	M16	43.0	A12×8×70
C5	300	230_{j6}	195	16	40_{k6}	265	4.0	166.0	286.0	80	5	14	M16	43.0	A12×8×70
C6	300	230_{j6}	225	17	50_{k6}	265	4.0	195.0	310.0	100	5	14	M16	53.5	A14×9×90
C7	350	250_{h6}	265	18	60_{m6}	300	5.0	231.0	371.0	120	5	18	M20	64.0	A18×11×100
C8	400	300_{h6}	310	20	70_{m6}	350	5.0	285.0	445.0	140	5	18	M20	74.5	A20×12×125
C9	450	350_{h6}	365	23	90_{m6}	400	5.0	334.0	524.0	170	5	18	M24	95.0	A25×14×140

Dimensions of additional round flanges

Type	Øa1	Øb1	c1	Øe1	f1	Øs1
C0	120	80_{j6}	10	100	3.0	7
C0	140	95_{j6}	10	115	3.0	9
C1	140	95_{j6}	8	115	3.5	9
C1	160	110_{j6}	10	130	3.5	9
C2	160	110_{j6}	10	130	3.5	9
C2	250	180_{j6}	12	215	4.0	14
C3	160	110_{j6}	10	130	3.5	9
C3	200	130_{j6}	12	165	3.5	11
C4	200	130_{j6}	14	165	3.5	11
C4	300	230_{j6}	14	265	4.0	14
C5	250	180_{j6}	14	215	4.0	14
C8	350	250_{h6}	18	300	5.0	18
C8	450	350_{h6}	20	400	5.0	18

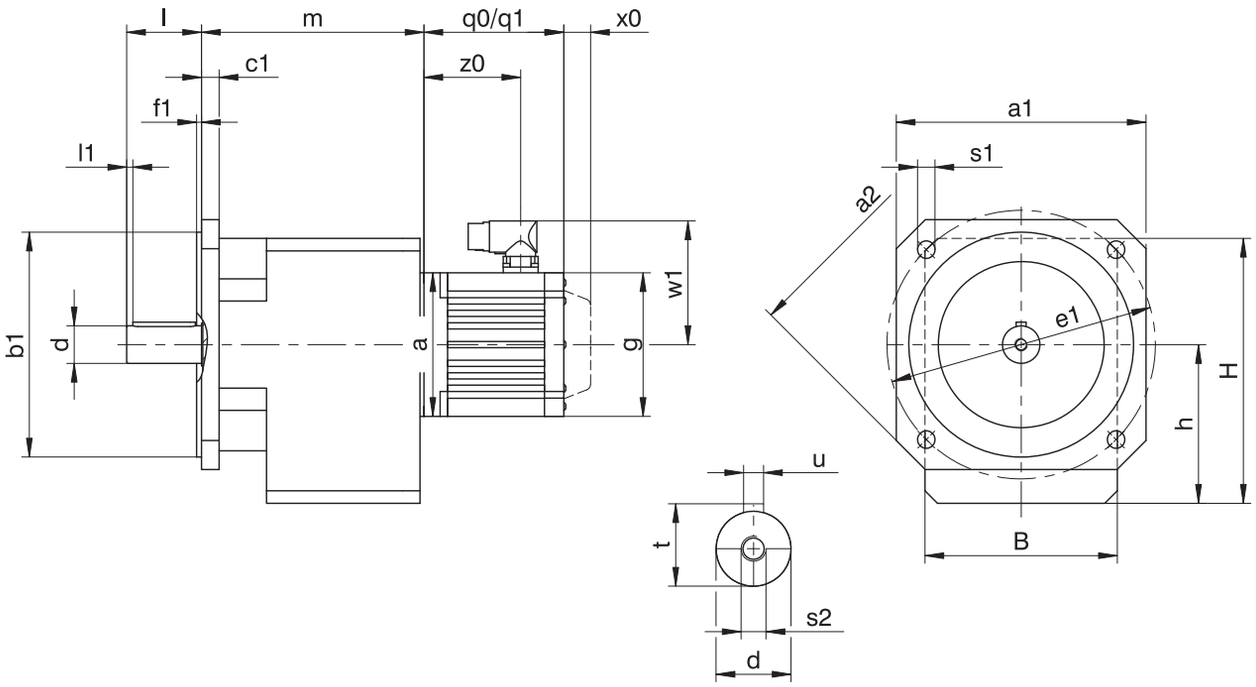
Dimensions of motors

Type	□g	q0	q1	w1	x0	z0
EZ203U	55	166.0	175.0	47.0	25	111.0
EZ301U	72	114.0	154.0	55.5	21	78.5
EZ302U	72	136.0	176.0	55.5	21	100.5
EZ303U	72	158.0	198.0	55.5	21	122.5
EZ401U	98	118.5	167.0	91.0	22	76.5
EZ402U	98	143.5	192.0	91.0	22	101.5
EZ404U	98	193.5	242.0	91.0	22	151.5
EZ501U	115	112.0	166.5	100.0	22	77.5
EZ502U	115	137.0	191.5	100.0	22	102.5
EZ503U	115	162.0	216.5	100.0	22	127.5
EZ505U	115	212.0	266.5	100.0	22	177.5
EZ701U	145	125.0	184.0	115.0	22	87.0
EZ702U	145	150.0	209.0	115.0	22	112.0
EZ703U	145	175.0	234.0	115.0	22	137.0
EZ705U	145	230.0	289.0	134.0	22	188.0
EZ802U	190	232.5	309.5	156.5	22	178.5
EZ803U	190	273.5	350.5	156.5	22	219.5
EZ805U	190	355.5	432.5	156.5	22	301.5

Dimensions of geared motors

Type	EZ2		EZ3		EZ4		EZ5		EZ7		EZ8	
	a	m	a	m	a	m	a	m	a	m	a	m
C002	□55	114	□72	114	□98	114	□115	118	□145	120	–	–
C102	–	–	□72	137	□98	137	□115	141	□145	143	–	–
C103	–	–	∅140	174	–	–	–	–	–	–	–	–
C202	–	–	∅140	155	∅140	155	□115	159	□145	161	–	–
C203	–	–	∅140	192	∅140	192	–	–	–	–	–	–
C302	–	–	–	–	–	–	∅160	178	□145	180	□190	183
C303	–	–	∅140	211	∅140	211	∅160	221	–	–	–	–
C402	–	–	–	–	–	–	∅160	206	□145	208	□190	211
C403	–	–	–	–	–	–	∅160	249	–	–	–	–
C502	–	–	–	–	–	–	∅160	227	∅200	229	□190	232
C503	–	–	–	–	–	–	∅160	270	–	–	–	–
C612	–	–	–	–	–	–	–	–	∅200	233	□190	236
C613	–	–	–	–	–	–	∅160	275	∅200	295	–	–
C712	–	–	–	–	–	–	–	–	∅200	266	∅250	268
C713	–	–	–	–	–	–	–	–	∅200	327	∅250	339
C812	–	–	–	–	–	–	–	–	–	–	∅250	315
C813	–	–	–	–	–	–	–	–	∅200	374	∅250	386
C913	–	–	–	–	–	–	–	–	–	–	∅250	423

7.3.4 Solid shaft design with feather key, Q housing design (square flange)



q0	Applies to motors without brake.	q1	Applies to motors with brake.
x0	EZ2: Applies only to motors with brake and encoders using an optical or inductive measuring method EZ3 – EZ8: Applies to encoders using an optical measuring method	w1	Different for the One Cable Solution (OCS), see the chapter [▶ 17.4]

C203, C303: Motor and gear unit are sometimes non-coaxial.

Options: C0 – C4 also available with solid shaft without feather key.

Dimensions of gear units

Type	□a1	□a2	Øb1	B	c1	Ød	Øe1	f1	h	H	l	l1	Øs1	s2	t	u
C0	124	160	110_{j6}	97	9	20_{k6}	130	3.0	79.0	141.0	40	3	9	M6	22.5	A6×6×32
C1	145	192	130_{j6}	130	11	25_{k6}	165	3.5	100.0	175.0	50	5	11	M10	28.0	A8×7×40
C2	145	192	130_{j6}	142	11	30_{k6}	165	3.5	112.0	192.0	60	5	11	M10	33.0	A8×7×50
C3	200	250	180_{j6}	154	14	30_{k6}	215	4.0	127.0	212.0	60	5	14	M10	33.0	A8×7×50
C4	200	250	180_{j6}	178	14	40_{k6}	215	4.0	142.5	242.5	80	5	14	M16	43.0	A12×8×70

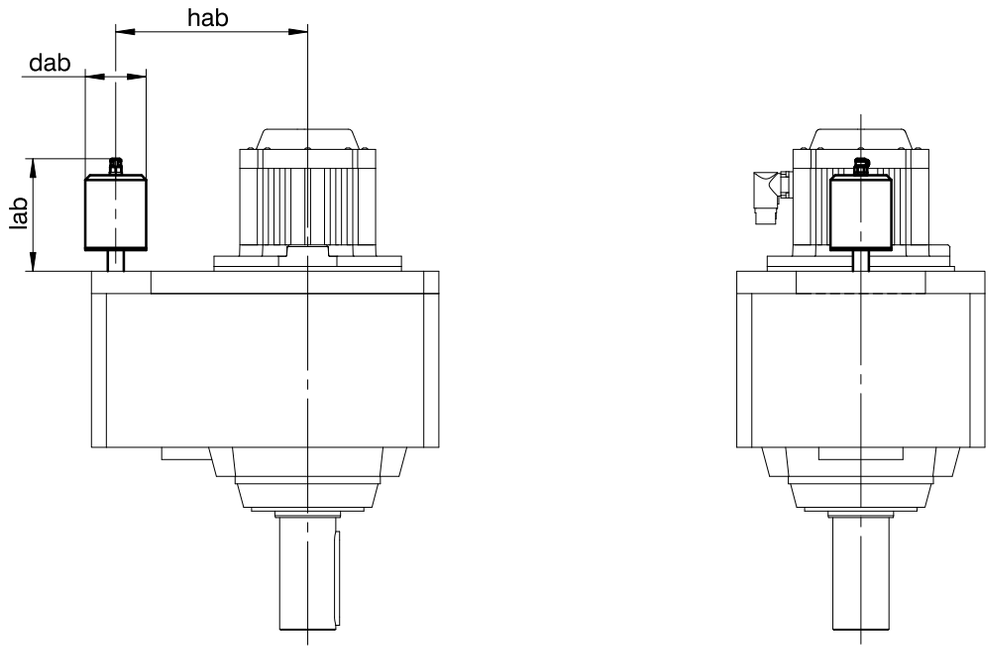
Dimensions of motors

Type	□g	q0	q1	w1	x0	z0
EZ203U	55	166.0	175.0	47.0	25	111.0
EZ301U	72	114.0	154.0	55.5	21	78.5
EZ302U	72	136.0	176.0	55.5	21	100.5
EZ303U	72	158.0	198.0	55.5	21	122.5
EZ401U	98	118.5	167.0	91.0	22	76.5
EZ402U	98	143.5	192.0	91.0	22	101.5
EZ404U	98	193.5	242.0	91.0	22	151.5
EZ501U	115	112.0	166.5	100.0	22	77.5
EZ502U	115	137.0	191.5	100.0	22	102.5
EZ503U	115	162.0	216.5	100.0	22	127.5
EZ505U	115	212.0	266.5	100.0	22	177.5
EZ701U	145	125.0	184.0	115.0	22	87.0
EZ702U	145	150.0	209.0	115.0	22	112.0
EZ703U	145	175.0	234.0	115.0	22	137.0
EZ705U	145	230.0	289.0	134.0	22	188.0
EZ802U	190	232.5	309.5	156.5	22	178.5
EZ803U	190	273.5	350.5	156.5	22	219.5
EZ805U	190	355.5	432.5	156.5	22	301.5

Dimensions of geared motors

Type	EZ2		EZ3		EZ4		EZ5		EZ7		EZ8	
	a	m	a	m	a	m	a	m	a	m	a	m
C002	□55	114	□72	114	□98	114	□115	118	□145	120	–	–
C102	–	–	□72	137	□98	137	□115	141	□145	143	–	–
C103	–	–	∅140	174	–	–	–	–	–	–	–	–
C202	–	–	∅140	155	∅140	155	□115	159	□145	161	–	–
C203	–	–	∅140	192	∅140	192	–	–	–	–	–	–
C302	–	–	–	–	–	–	∅160	178	□145	180	□190	183
C303	–	–	∅140	211	∅140	211	∅160	221	–	–	–	–
C402	–	–	–	–	–	–	∅160	206	□145	208	□190	211
C403	–	–	–	–	–	–	∅160	249	–	–	–	–

7.3.5 Oil expansion tank



Dimensions

Type	EZ7			EZ8		
	dab	hab	lab	dab	hab	lab
C612	65	170	114.5	65	170	112
C712	73	205	129.5	73	205	129.5

More information can be found in Chapter [▶ 7.6.4]

7.4 Type designation

This chapter shows you an explanation of the type designation with the associated options.

Additional ordering information not included in the type designation can be found at the end of the chapter.

Example code

C	2	0	2	N	0280	EZ401U

Explanation

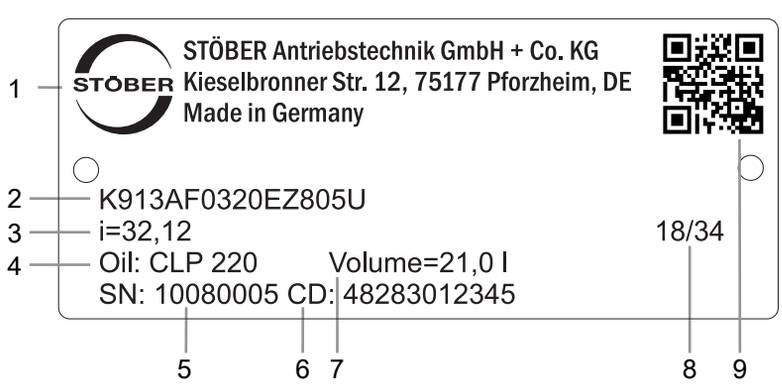
Code	Designation	Design
C	Type	Helical gear unit
2	Size	2 (example)
0	Generation	Generation 0
1		Generation 1
2	Stages	Two-stage
3		Three-stage
G	Housing	Pitch circle diameter
F		Round flange
Q		Square flange
N		Foot
0280	Transmission ratio (i x 10 rounded)	i = 28.24 (example)
EZ401U	Motor	EZ synchronous servo motor

To complete the type designation, also specify the following in your order:

- For a detailed type designation of the motor, see the chapter [▶ 17]
- For the mounting position, see the chapter [▶ 7.5.5]
- Position of the plug connectors, see the chapter [▶ 7.5.7]
- Oil expansion tank (option, recommended for gear units in mounting position EL5), see the chapter [▶ 7.6.4]

7.4.1 Nameplate

An example gear unit nameplate is explained in the figure below.



Code	Designation
1	Name of manufacturer
2	Type designation
3	Gear ratio of the gear unit
4	Lubricant specification
5	Serial number of the gear unit
6	Customer-specific data
7	Lubricant fill volume
8	Date of manufacture (year/calendar week)
9	QR code (link to product information)

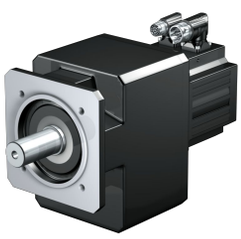
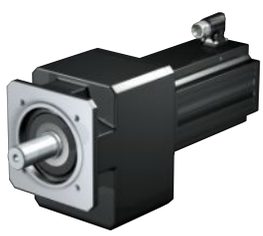
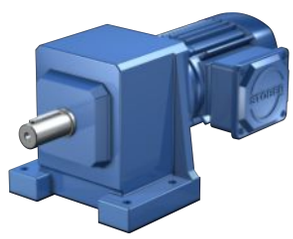
7.4.1.1 Supporting documents

You can view or download supporting documents for the product by reading off the serial number on the nameplate of the product and entering it at the following address online:
https://id.stober.com

Alternatively, you can use a suitable mobile device to scan in the QR code on the nameplate of the product in order to be linked to the supporting documents.

7.5 Product description

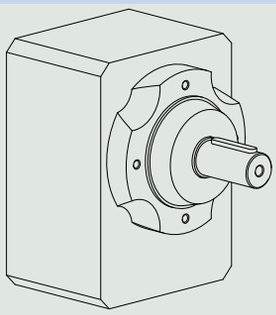
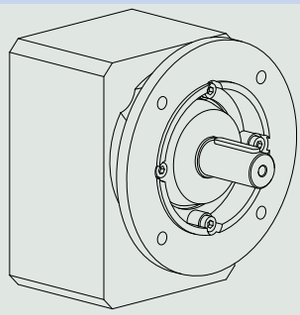
7.5.1 Input options

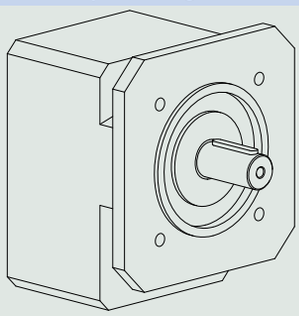
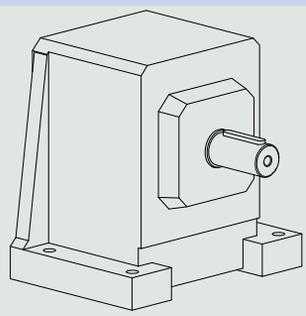
EZ synchronous servo motor	MB motor adapter + EZ synchronous servo motor	LM Lean motor	Asynchronous motor
			
Catalog ID 442437_en	Catalog ID 443311_en	Catalog ID 443016_en	Catalog ID 443136_en

The corresponding catalogs can be found at http://www.stoeber.de/en/downloads/

Enter the ID of the catalog in the Search term field.

7.5.2 Housing design

Pitch circle diameter G	Round flange F
	

Square flange Q	Foot N
	

	G	F	Q	N
C0	✓	✓	✓	✓
C1	✓	✓	✓	✓
C2	✓	✓	✓	✓
C3	✓	✓	✓	✓
C4	✓	✓	✓	✓
C5	✓	✓	–	✓
C6	✓	✓	–	✓
C7	✓	✓	–	✓
C8	✓	✓	–	✓
C9	✓	✓	–	✓

7.5.3 Shaft design

Gear units in sizes C0 – C9 come standard with a solid shaft with feather key.

Gear units in sizes C0 – C5 can be ordered with the option of a solid shaft without feather key. Only upon request starting at size C6.

7.5.4 Installation conditions

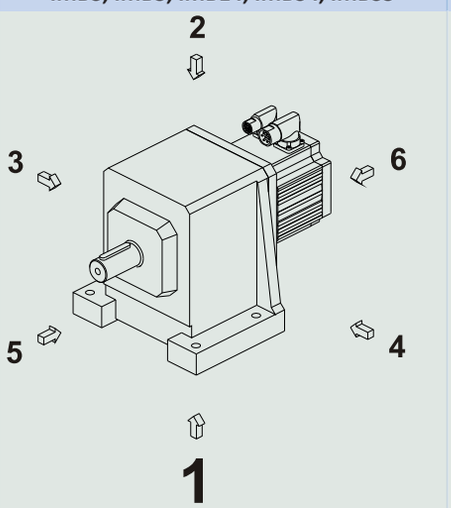
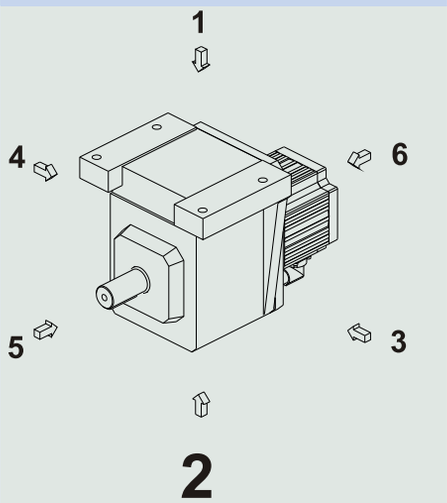
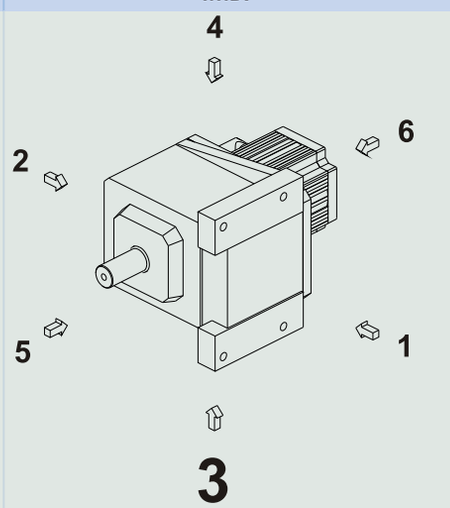
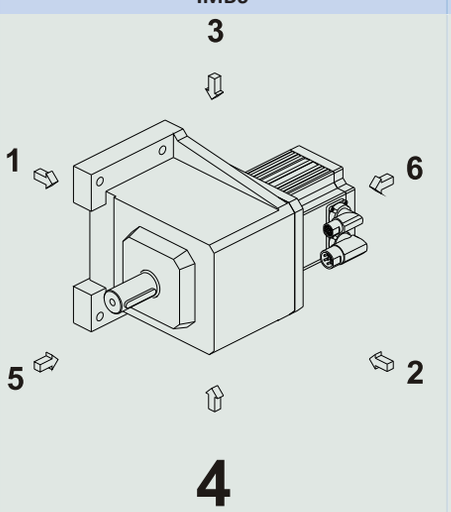
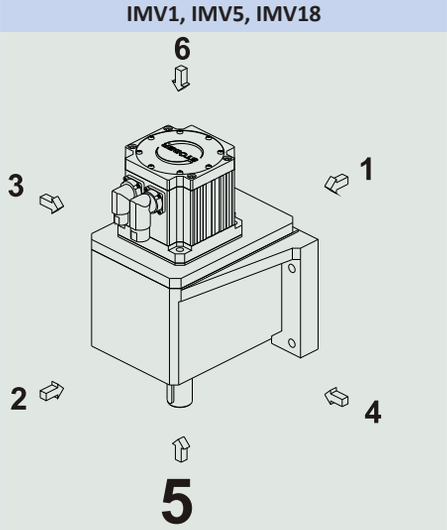
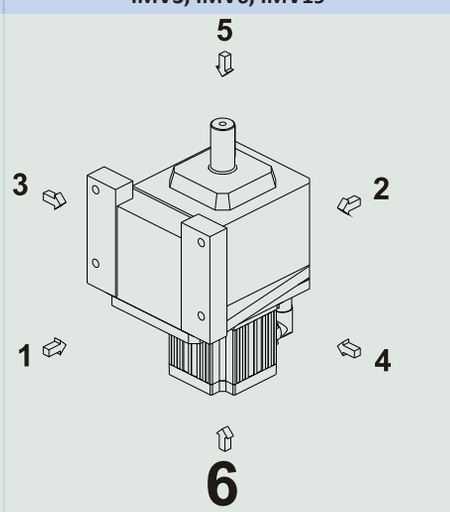
Fastening the gear units on the machine side using the pitch circle diameter

The specified torques and forces only apply when gear units are fastened on the machine side using screws of strength class 10.9. In addition, the gear housings must be adjusted at the pilot. The machine-side fit must be H7.

7.5.5 Mounting positions

The following table shows the standard mounting positions.

The numbers identify the gear unit sides. The mounting position is defined by the gear side facing downwards.

EL1 IMB3, IMB5, IMB14, IMB34, IMB35	EL2 IMB8	EL3 IMB7
		
EL4 **IMB6**	**EL5** **IMV1, IMV5, IMV18**	**EL6** **IMV3, IMV6, IMV19**
		

Since the lubricant filling volume of the gear unit depends on the mounting position, the mounting position must be specified when ordering.

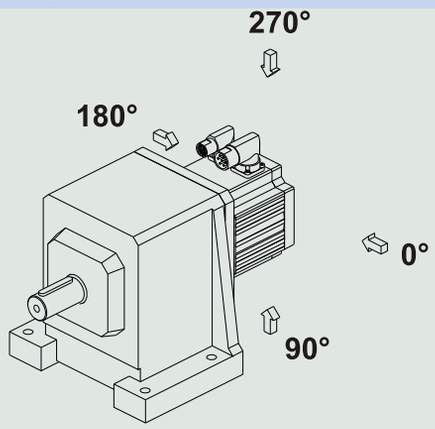
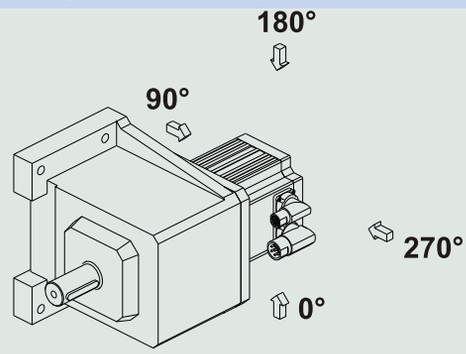
7.5.6 Lubricants

STOBER fills the gear units with the amount and type of lubricant specified on the nameplate. The filling volume and the structure of the gear units depend on the mounting position.

Only install the gear units in the intended mounting position! Reposition the gear units only after consulting STOBER. Otherwise, STOBER assumes no liability for the gear units.

You will receive lubricants for use in the food industry upon request.

7.5.7 Position of the plug connectors

Mounting position EL1	Mounting position EL4
Plug connector in 270° position (standard)	Plug connector in 270° position (standard)
	

Indicate variations for your geared motor in the order.

Note that the plug connector position rotates along with the geared motor if the geared motor is in another mounting position.

7.5.8 Other product features

Feature	Value
Max. permitted gear unit temperature (on the surface of the gear unit)	≤ 80 °C
Paint	Black RAL 9005
Explosion-proof design in accordance with (ATEX) Directive 2014/34/EU (optional)	Not available
Efficiency:	
η_{get} two-stage	97%
η_{get} three-stage	96%
Protection class:[1]	
Gear unit	IP65
Motor	IP56, optionally IP66

7.5.9 Maintenance

The instructions for maintenance can be found in the operating manual, ID 443027_en, at http://www.stoeber.de/en/downloads/. Enter the ID of the documentation in the Search... field.

Ventilation

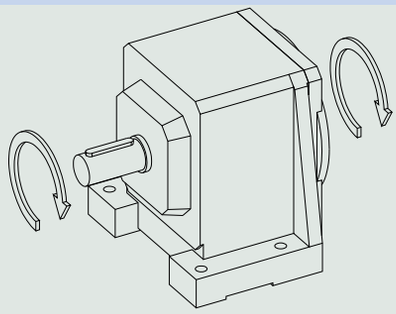
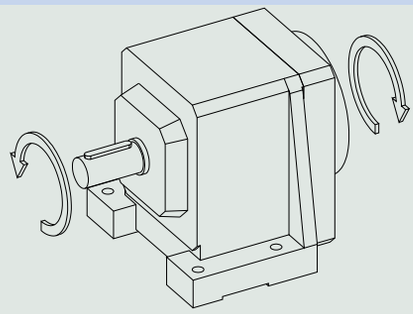
Air release valves are fitted as a standard feature and independently of installation position for gear unit sizes C6 to C9.

For the position and dimensions of the air release valve, refer to the 3D model.

Download the 3D model at https://configurator.stoeber.de/en-US/.

[1] Observe the protection class of all the components.

7.5.10 Direction of rotation

C002 – C912	C103 – C913
	
The input and output rotate in the same direction.	The input and output rotate in opposite directions.

The pictures show mounting position EL1.

7.6 Project configuration

Project your drives using our SERVOsoft designing software. Download SERVOsoft for free at https://www.stoeber.de/en/ServoSoft.

It is the most convenient and reliable method of drive selection, as the entire torque/speed curve of the application is displayed and evaluated here in the curve of the geared motor.

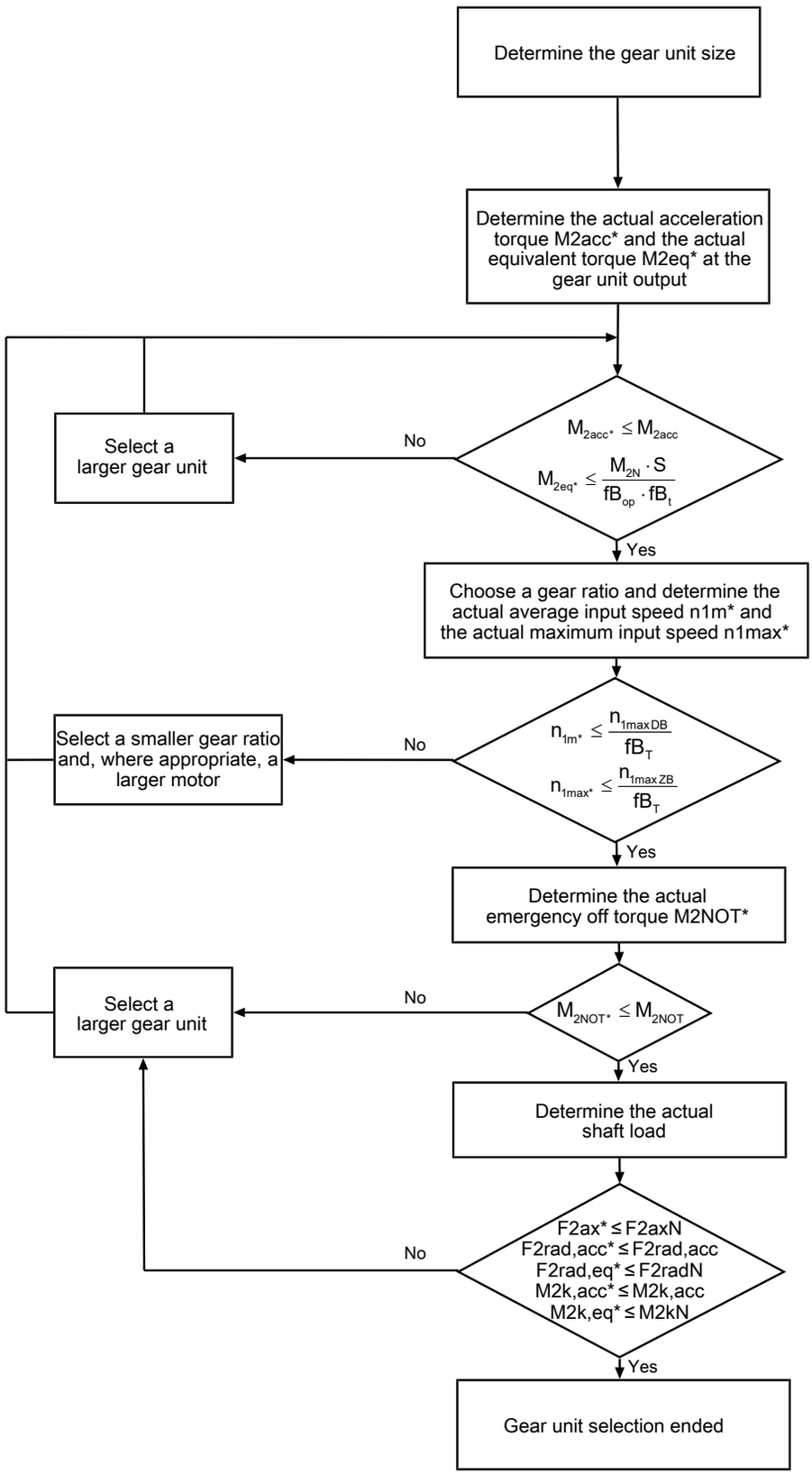
In this chapter, only limit values for specific operating points can be taken into consideration for manual drive selection.

An explanation of the formula symbols can be found in Chapter [▷ 20.1].

The formula symbols for values actually present in the application are marked with *.

7.6.1 Drive selection

Drive selection for gear units

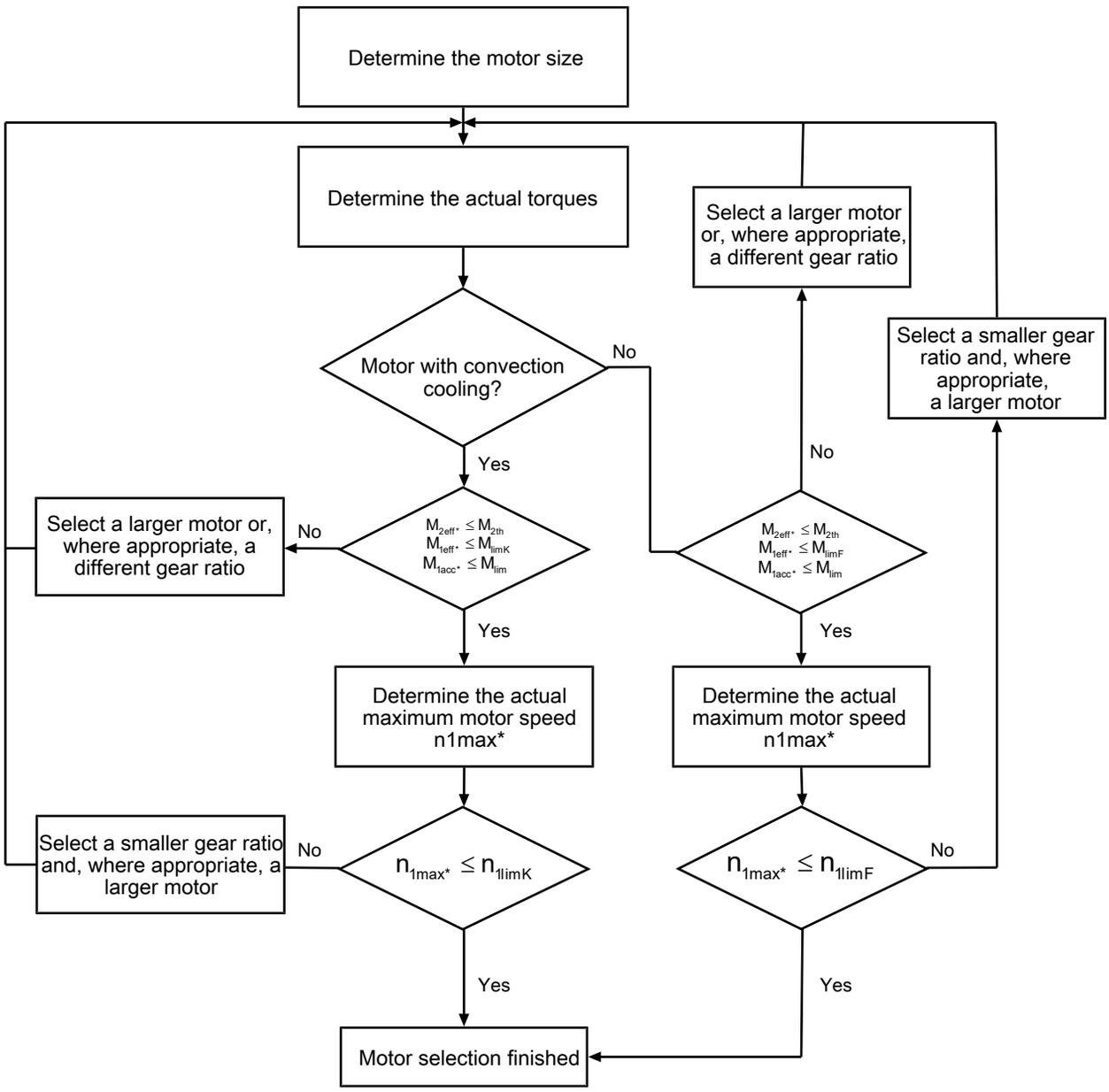


Calculate the forces and tilting torques in the chapter Permitted shaft loads.

Refer to the selection tables for the values for i, n_{1maxDB}, n_{1maxZB}, M_{2acc}, M_{2NOT}, M_{2N} and S.

The values for fB_T, fB_{op} and fB_t can be found in the corresponding tables in this chapter.

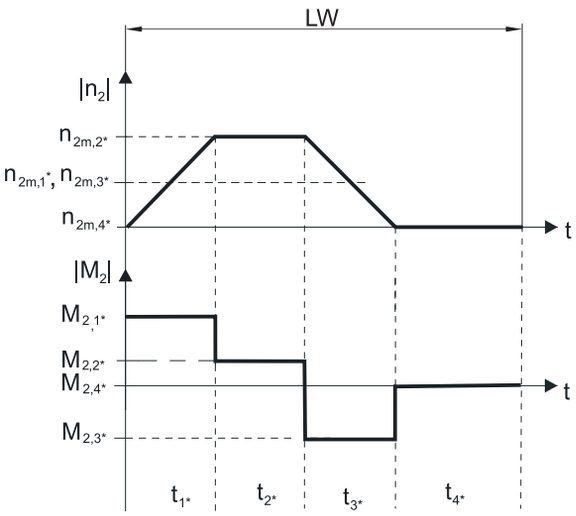
Drive selection for motors



The value for M_{lim}, M_{limK}, M_{limF}, n_{1limK} and n_{1limF} can be found in the motor characteristic curve in the chapter [▷ 17.3]. Note the size, nominal speed n_N and cooling type of the motor.

Example of cyclic operation

The following calculations are based on a representation of the power taken from the output based in accordance with the following example:



Calculation of the actual maximum acceleration torques

$$M_{2acc*} = J_{tot} \cdot \frac{\Delta n_2}{9{,}55 \cdot \Delta t} + M_{L*}$$

$$M_{1acc*} = \frac{M_{2acc*}}{i \cdot \eta_{get}} + J_1 \cdot \frac{\Delta n_1}{9{,}55 \cdot \Delta t}$$

Calculation of the actual average input speed

$$n_{1m*} = n_{2m*} \cdot i$$

$$n_{2m*} = \frac{\left|n_{2m,1*}\right| \cdot t_{1*} + \ldots + \left|n_{2m,n*}\right| \cdot t_{n*}}{t_{1*} + \ldots + t_{n*}}$$

If $t_{1*} + \ldots + t_{3*} \geq 6$ min, calculate n_{2m*} without the rest phase t_{4*}.

The values for the ratio i can be found in the selection tables.

Calculation of the actual effective torque

$$M_{2eff*} = \sqrt{\frac{t_{1*} \cdot M_{2,1*}{}^2 + \ldots + t_{n*} \cdot M_{2,n*}{}^2}{t_{1*} + \ldots + t_{n*}}}$$

Calculation of the actual emergency-off torque

$$M_{2NOT*} = J_{tot} \cdot \frac{\Delta n_2}{9.55 \cdot \Delta t} + M_{L*}$$

Calculation of the actual equivalent torque

$$M_{2eq*} = \sqrt[3]{\frac{\left|n_{2m,1*}\right| \cdot t_{1*} \cdot \left|M_{2,1*}{}^3\right| + \ldots + \left|n_{2m,n*}\right| \cdot t_{n*} \cdot \left|M_{2,n*}{}^3\right|}{\left|n_{2m,1*}\right| \cdot t_{1*} + \ldots + \left|n_{2m,n*}\right| \cdot t_{n*}}}$$

Calculation of the thermal limit torque

Calculate the thermal limit torque M_{2th} for a duty cycle $ED_{10} > 50\%$ and the actual average input speed n_{1m*}. (At $K_{mot,th} \leq 0$ you must reduce the average input speed n_{1m*} accordingly or select another geared motor size.)

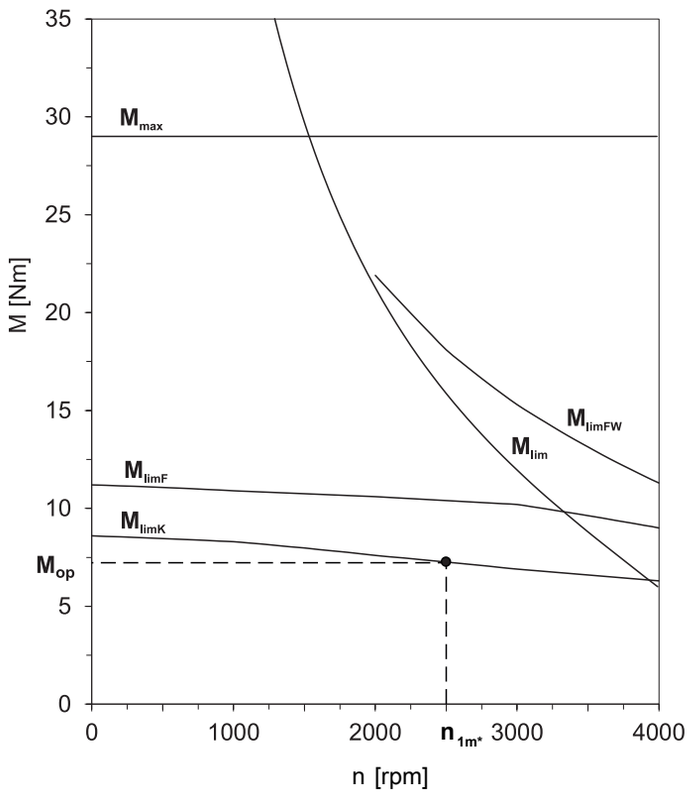
$$M_{2th} = M_{op} \cdot i \cdot K_{mot,th}$$

$$K_{mot,th} = 0{,}95 - \frac{a_{th}}{1000} \cdot athEL \cdot fB_T \cdot \left(\frac{n_{1m*}}{1000}\right)^3$$

The values for i and a_{th} can be found in the selection tables.

The values for a_{thEL} and fB_T can be found in the corresponding tables in this chapter.

The value for the torque of the motor at operating point M_{op} with the determined average input speed n_{1m*} can be found in the motor characteristic curve in the chapter [▶ 17.3]. Note the size, nominal speed n_N and cooling type of the motor. The figure below shows an example of reading the torque M_{op} of a motor with convection cooling at the operating point.



Operating factors

Parameter a_{thEL}

Mounting position	a_{thEL}
EL1, 2, 5, 6	1.0
EL3, 4	1.1

Operating mode	fB_{op}
Uniform continuous operation	1.00
Cyclic operation	1.25
Reversing load cyclic operation	1.40

Run time	fB_t
Daily runtime ≤ 8 h	1.00
Daily runtime ≤ 16 h	1.15
Daily runtime ≤ 24 h	1.20

Temperature		fB_T
Motor cooling	**Surrounding temperature**	
Motor with forced ventilation	≤ 20 °C	0.9
	≤ 30 °C	1.0
	≤ 40 °C	1.15
Motor with convection cooling	≤ 20 °C	1.0
	≤ 30 °C	1.1
	≤ 40 °C	1.25

Notes

- The maximum permitted gear unit temperature (see the "Other product features" chapter) must not be exceeded. Doing so may result in damage to the geared motor.
- For braking from full speed (for example when the power fails or when setting up the machine), note the permitted gear unit torques (M_{2acc}, M_{2NOT}) in the selection tables.

7.6.2 Permitted shaft loads for the output shaft

The values specified in the tables apply to the permitted shaft loads:

- For shaft dimensions in accordance with the catalog
- For output speeds $n_{2m*} \leq 20$ rpm ($F_{2axN} = F_{2ax20}$; $F_{2radN} = F_{2rad20}$; $M_{2kN} = M_{2k20}$)
- Only if radial forces on the gear unit are stabilized by its pilots for the pitch circle diameter and flange housing design

Permitted shaft loads

Type	z_2	F_{2ax20}	F_{2rad20}	$F_{2rad,acc}$	M_{2k20}	$M_{2k,acc}$
	[mm]	[N]	[N]	[N]	[Nm]	[Nm]
C0	20.0	500	1900	1900	80	80
C1	30.0	850	3400	3400	190	190
C2	30.0	1050	4200	4200	260	260
C3	30.0	1400	5650	5650	350	350
C4	35.0	2400	9700	9700	750	750
C5	42.0	3000	11000	11000	900	900
C6	40.0	4000	16000	16000	1500	1500
C7	45.0	5500	22000	22000	2400	2400
C8	50.0	7500	30000	30000	3700	3700
C9	55.0	9500	37000	37000	5200	5200

For other output speeds, download diagrams at https://configurator.stoeber.de/en-US/.

The following applies to output speeds $n_{2m*} > 20$ rpm:

$$F_{2axN} = \frac{F_{2ax20}}{\sqrt[3]{\frac{n_{2m*}}{20\ \text{rpm}}}} \qquad F_{2radN} = \frac{F_{2rad20}}{\sqrt[3]{\frac{n_{2m*}}{20\ \text{rpm}}}} \qquad M_{2kN} = \frac{M_{2k20}}{\sqrt[3]{\frac{n_{2m*}}{20\ \text{rpm}}}}$$

The values for F_{2ax20}, F_{2rad20} and M_{2k20} can be found in the table "Permitted shaft loads" in this chapter.

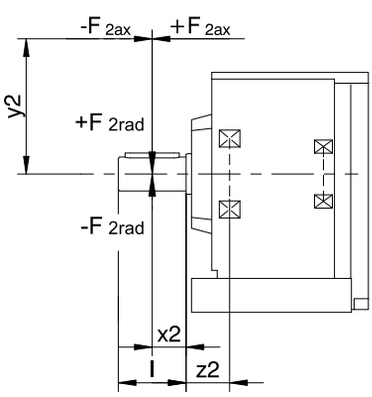


Fig. 1: Force application points

The specified values for F_{2rad20} and $F_{2rad,acc}$ refer to an application of force at the center of the output shaft: $x_2 = l/2$.

Shaft dimensions can be found in the "Dimensional drawings" chapter.

The following applies to other force application points:

$$M_{2k,acc*} = \frac{2 \cdot F_{2ax*} \cdot y_2 + F_{2rad,acc*} \cdot (x_2 + z_2)}{1000}$$

For applications with multiple axial and/or radial forces, you must add the forces as vectors.

In the event of EMERGENCY OFF operation (max. 1000 load changes), you can multiply the permitted forces and torques for F_{2ax20}, F_{2rad20} and M_{2k20} by a factor of two.

Also note the calculation for equivalent values:

$$M_{2k,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*}| \cdot t_{1^*} \cdot |M_{2k,acc,1^*}^{\ 3}| + \ldots + |n_{2m,n^*}| \cdot t_{n^*} \cdot |M_{2k,acc,n^*}^{\ 3}|}{|n_{2m,1^*}| \cdot t_{1^*} + \ldots + |n_{2m,n^*}| \cdot t_{n^*}}}$$

$$F_{2rad,eq^*} = \sqrt[3]{\frac{|n_{2m,1^*}| \cdot t_{1^*} \cdot |F_{2rad,acc,1^*}^{\ 3}| + \ldots + |n_{2m,n^*}| \cdot t_{n^*} \cdot |F_{2rad,acc,n^*}^{\ 3}|}{|n_{2m,1^*}| \cdot t_{1^*} + \ldots + |n_{2m,n^*}| \cdot t_{n^*}}}$$

7.6.3 Radial shaft seal rings

Leak-proofness

Our gear units are equipped with high-quality radial shaft seal rings and checked for leaks. However, a leak cannot be fully ruled out over the length of use of a gear unit. If you use a gear unit with goods incompatible with the lubricant, you must take measures to prevent direct contact with the gear unit lubricant in case of a leak.

7.6.4 Oil expansion tank

The gear units have a higher fill level in mounting position EL5. The oil expansion tank prevents oil from escaping out of the gear unit.

Notes

- We recommend using an oil expansion tank in mounting position EL5 (additional cost) for fast running gear units with an input speed $n_1 > 1750$ rpm and gear ratios $i < 20$.
- It is not possible to use an oil expansion tank if the plug connector is at 90°!
- The oil expansion tank can only be used with certain sizes; see the chapter [▷ 7.3.5]

7.7 Additional documentation

Additional documentation related to the product can be found at
http://www.stoeber.de/en/downloads/

Enter the ID of the documentation in the Search term field.

Documentation	ID
Operating manual gear units, geared motors C	443365_en