

1 Safety information

1.1 General safety instructions

⚠ WARNING!

When connecting and operating the motors considerable hazards to the life and health of persons may occur!

- ▶ When connecting the motor observe the following safety instructions, the operating instructions for the motor and applicable national, local and system-specific regulations.

1.2 Safety when making the electrical connection

⚠ WARNING!

Electrical shock by touching live unpainted parts of the motor!

- ▶ The electrical connection of the motor may only be carried out by a qualified electrician.
- ▶ Before connecting the motor, switch the relevant system or machine to zero potential with the main switch and protect the main switch against being turned on again!
- ▶ Close the entire connector housing before turning on the motor.
- ▶ Do not touch the motor connections while the motor shaft is rotating, as due to the built-in permanent magnets a voltage is applied to the motor connections.

1.3 Avoid connection errors

NOTICE

Electrical connection errors can cause damage to the motor and its components.

- ▶ Make sure that the cables and connectors to be connected meet this motor connection plan.
- ▶ Carefully note the information on the motor name plate and this motor connection plan. For questions please contact STÖBER Service department.

1.4 Risks of noncoordinated third-party components

NOTICE

If connection cables or a drive controller that are not designed for the motor are used to make the electrical connection for the motor, this may result in damage to the motor or that compliance with the legal requirements for EMC is no longer provided and claims under the warranty will be null and void.

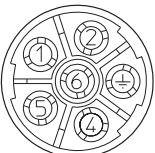
- ▶ You should use connection cables and a drive controller specifically designed for your motor from the STÖBER product range.

1.5 Applied standards

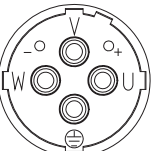
Colors are coded as per IEC 60757 and are only relevant for the internal motor connection strands.

2 Motor connection

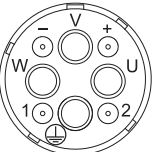
2.1 Power connection via connector

Connection diagram	Pin	Designation	Color
 <p>Size con.23 (1)</p>	1	1U1 (phase U)	BK
	2	1V1 (phase V)	BU
	4	1BD1 ¹⁾	
	5	1BD2 ¹⁾	
	6	1W1 (phase W)	RD
	⊕	Protective conductor	GNYE

1) see chapter "Motor holding brake"

Connection diagram	Pin	Designation	Color
 <p>Size con.40 (1,5)</p>	U	1U1 (phase U)	BK
	V	1V1 (phase V)	BU
	W	1W1 (phase W)	RD
	+	1BD1 ¹⁾	
	-	1BD2 ¹⁾	
	⊕	Protective conductor	GNYE

1) see chapter "Motor holding brake"

Connection diagram	Pin	Designation	Color
 <p>Size con.58 (3)</p>	U	1U1 (phase U)	BK
	V	1V1 (phase V)	BU
	W	1W1 (phase W)	RD
	+	1BD1 ¹⁾	
	-	1BD2 ¹⁾	
	1		
	2		
⊕	Protective conductor	GNYE	

1) see chapter "Motor holding brake"

2.2 Temperature sensor



Information

The temperature sensor of the synchronous servomotor is internally connected to the encoder. Therefore, read the measured values of the temperature sensor via the communication protocol of the encoder from.

2.3 Motor holding brake (optional)

NOTICE

The brake can be damaged by electrical connection errors!

- ▶ When connecting the brake, carefully note the polarity of the connections and the supply voltage of the brake.


Permanent magnet brake (P)		
Abbreviation	Designation	Color
1BD1	DC 24 V ± 5 % (smoothed)	RD
1BD2	0 V (GND)	BK

2.4 External fan connection (optional)

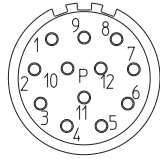
NOTICE

The external fan motor can be damaged by electrical connection errors!

- Check before making the connection whether the connection values and terminal assignment of the external fan motor match those shown below.

Connection diagram	Pin	Designation
	1	L1 (230 V ± 5 %, 50/60 Hz)
	2	N
	3	
		Protective conductor

2.5 Encoder connection via connector

Absolute value encoder EnDat 2.2 digital			
Connection diagram	Pin	Signal	Color
 <p>Size con.23</p>	1	Clock +	VT
	2		
	3		
	4		
	5	Data –	PK
	6	Data +	GY
	7		
	8	Clock –	YE
	9		
	10	0 V	WHGN
	11		
	12	Up +	BNGN