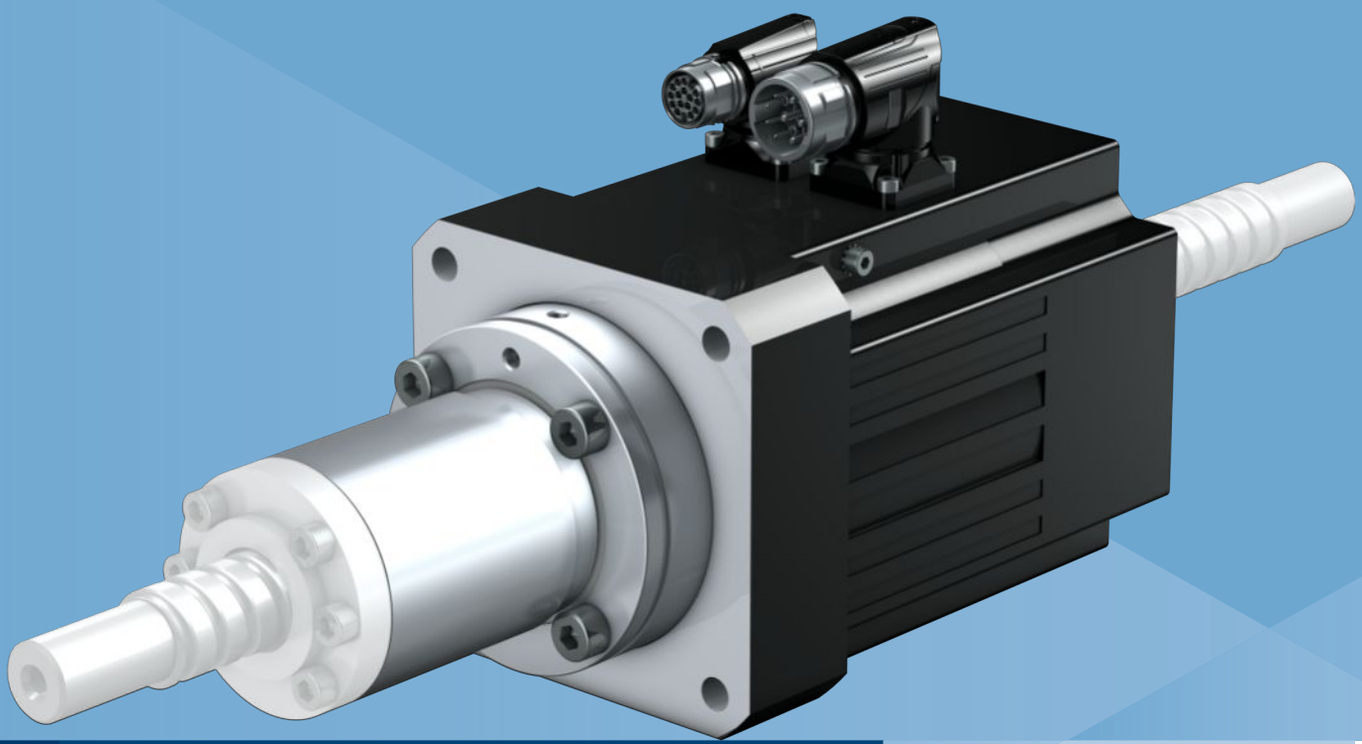


19

Synchronous servo motors for screw drives

EZM

19.1 Overview

Synchronous servo motor for screw drives (direct drive for threaded nut)

Features

Designed for driving the ball-threaded nut of ball screws in accordance with DIN 69051-2.	✓
Axial angular contact ball bearing acting on two sides for direct absorption of the threaded spindle forces	✓
Super compact due to tooth-coil winding method with the highest possible copper fill factor	✓
Backlash-free holding brake (optional)	✓
Convection cooling	✓
Inductive EnDat absolute encoders	✓
Elimination of referencing with multi-turn absolute encoders (optional)	✓
Electronic nameplate for fast and reliable commissioning	✓
Rotatable plug connectors with quick lock	✓

Axial forces

F_{ax}	751 – 21375 N

19.2 Selection tables

The technical data specified in the selection tables applies to:

- Installation altitudes up to 1000 m above sea level
- Surrounding temperatures from −15 °C to +40 °C
- Operation on a STOBER drive controller
- DC link voltage U_{ZK} = DC 540 V
- Coating: RAL 9005 Jet black, matte

In addition, the technical data applies to an uninsulated design with the following thermal mounting conditions:

Type	Dimensions of steel mounting flange (thickness x width x height)	Convection surface area Steel mounting flange
EZM5	23 x 210 x 275 mm	0.16 m^2
EZM7	28 x 300 x 400 mm	0.3 m^2

Formula symbols

An explanation of the formula symbols can be found in Chapter [▷ 23.1].

Observe the additional information on the following formula symbols:

- I_0 = RMS value of the line-to-line current when stall torque M_0 is generated (tolerance ±5%).
- I_{max} = RMS value of the short-term maximum permitted line-to-line current when maximum torque M_{max} is generated (tolerance ±5%). Exceeding I_{max} may lead to irreversible damage (demagnetization) of the rotor.
- I_N = RMS value of the line-to-line current when nominal torque M_N is generated at the nominal point (tolerance ±5%).
- M_0 = Torque that a motor is continuously able to deliver at a speed of 10 rpm (tolerance ±5%). At a speed of 0 rpm, a minor continuous torque has to be taken into account. Contact your STOBER customer advisor for such an application.

Type	K_{EM} [V/1000 rpm]	n_N [rpm]	M_N [Nm]	I_N [A]	$K_{M,N}$ [Nm/A]	P_N [kW]	M_0 [Nm]	I_0 [A]	K_{M0} [Nm/A]	M_R [Nm]	M_{max} [Nm]	I_{max} [A]	R_{U-V} [Ω]	L_{U-V} [mH]	T_{el} [ms]
EZM511U	97	3000	3.65	3.55	1.03	1.2	4.25	4.00	1.19	0.49	16.0	22.0	3.80	23.50	6.18
EZM512U	121	3000	6.60	5.20	1.27	2.1	7.55	5.75	1.40	0.49	31.0	33.0	2.32	16.80	7.24
EZM513U	119	3000	8.80	6.55	1.34	2.8	10.6	7.60	1.46	0.49	43.0	41.0	1.25	10.00	8.00
EZM711U	95	3000	6.35	6.60	0.96	2.0	7.30	7.40	1.07	0.65	20.0	25.0	1.30	12.83	9.87
EZM712U	133	3000	10.6	7.50	1.41	3.3	13.0	8.90	1.53	0.65	41.0	36.0	1.00	11.73	11.73
EZM713U	122	3000	14.7	10.4	1.41	4.6	18.9	13.0	1.50	0.65	65.0	62.0	0.52	6.80	13.08

19.2.1 Mass moments of inertia and weights

	df [mm]	ef [mm]	ef2 [mm]	J [kgcm²]	m [kg]
EZM511	40	51	65	20.3	9.9
EZM512	40	51	65	23.6	11.5
EZM513	40	51	65	26.8	13.1
EZM711	56	71	78	60.3	17.6
EZM711	50	65	78	53.7	17.4
EZM712	56	71	78	69.7	20.1
EZM712	50	65	78	63.1	19.9
EZM713	56	71	78	79.0	22.7
EZM713	50	65	78	72.4	22.5

19.3 Torque/speed curves

Torque/speed curves depend on the nominal speed and/or winding design of the motor and the DC link voltage of the drive controller that is used. The following torque/speed curves apply to the DC link voltage DC 540 V.

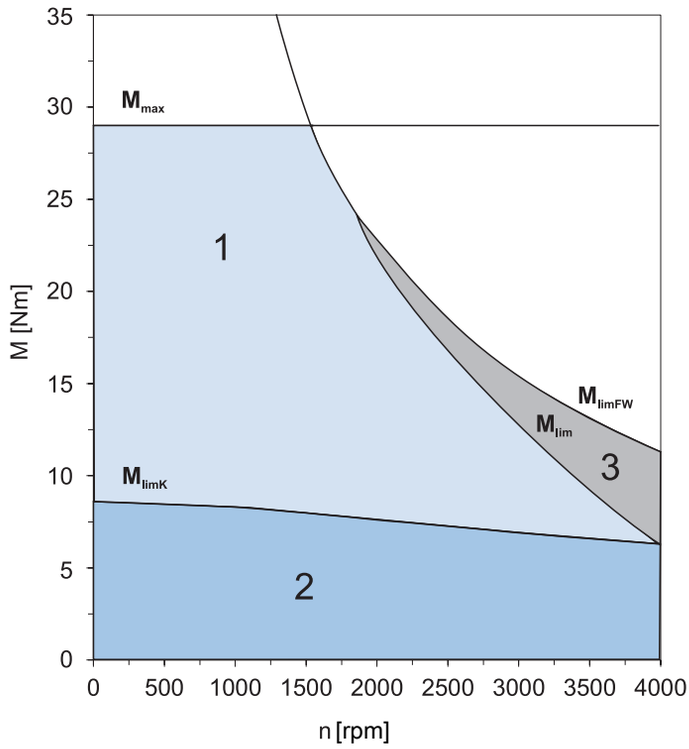
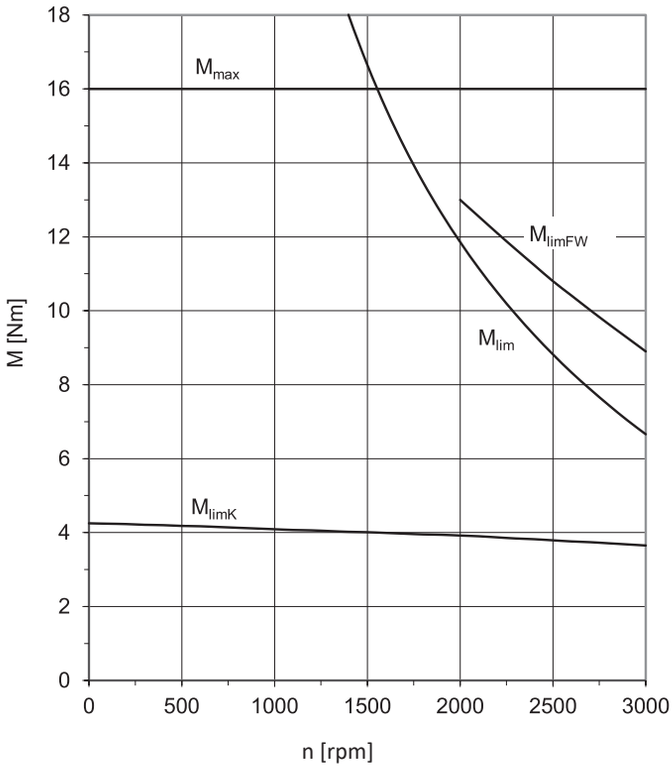


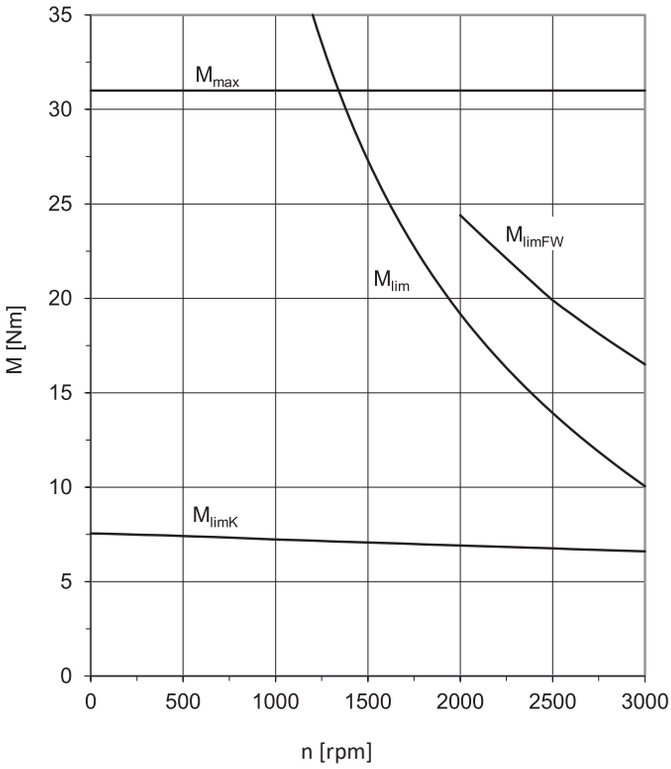
Fig. 1: Explanation of a torque/speed curve

1	Torque range for brief operation (ED_{10} < 100%) with $\Delta\vartheta$ = 100 K	2	Torque range for continuous operation with constant load (S1 mode, ED_{10} = 100%) with $\Delta\vartheta$ = 100 K
3	Field weakening range (can be used only with operation on STOBER drive controllers)		

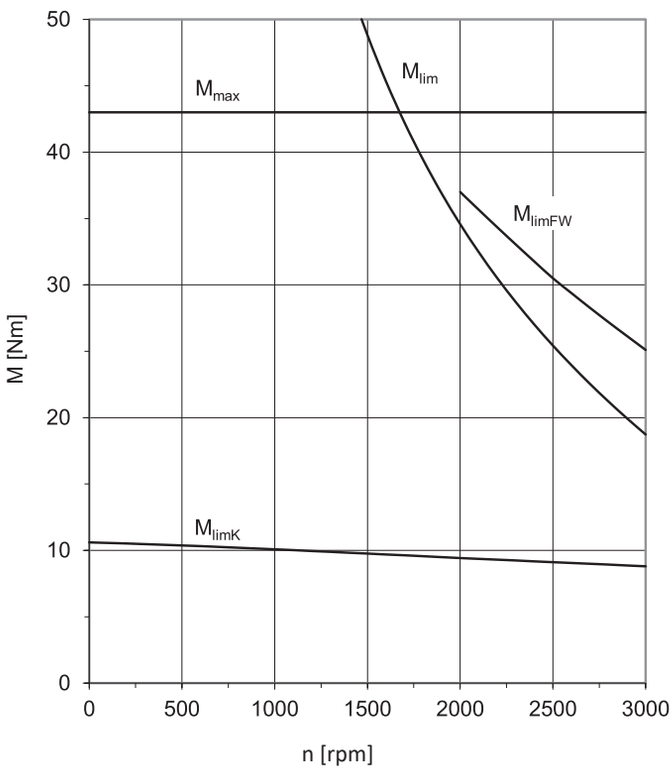
EZM511 (n_N=3000 rpm)



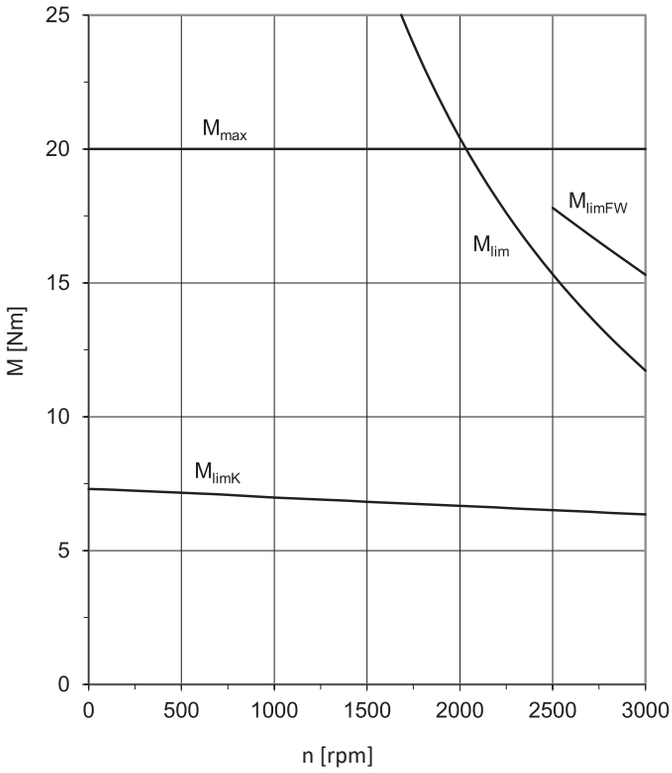
EZM512 (n_N=3000 rpm)



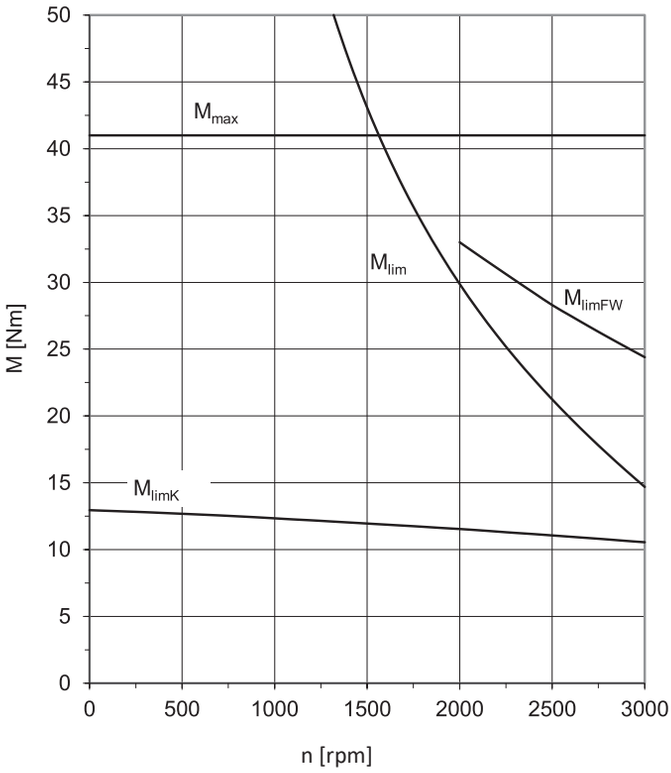
EZM513 (n_N=3000 rpm)



EZM711 (n_N=3000 rpm)



EZM712 (n_N=3000 rpm)



EZM713 (n_N=3000 rpm)